

**Lecture 1:**

# **Course Introduction: Welcome to Computer Graphics!**

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**Interactive Computer Graphics  
Stanford CS248, Winter 2020**

## **Gift of Gab**

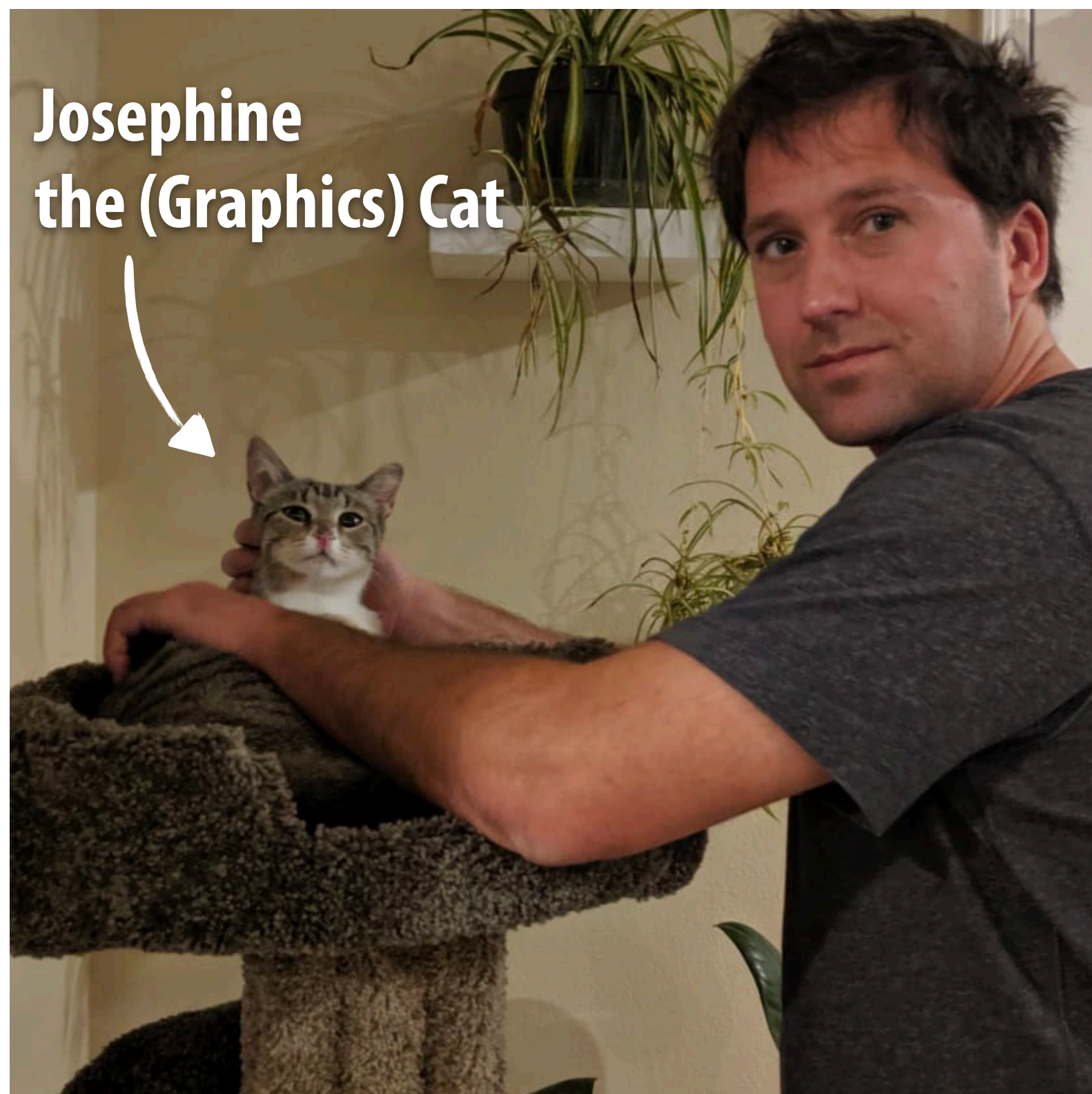
### **“Dreamin”**

**(Escape to Mars)**

*“Think of all the things you will be able to create with a bit of graphics knowledge.”*  
*- Timothy Jerome Parker*

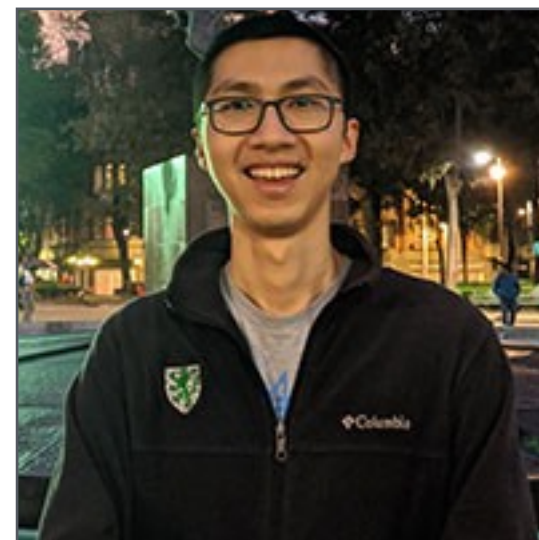


# Hi!

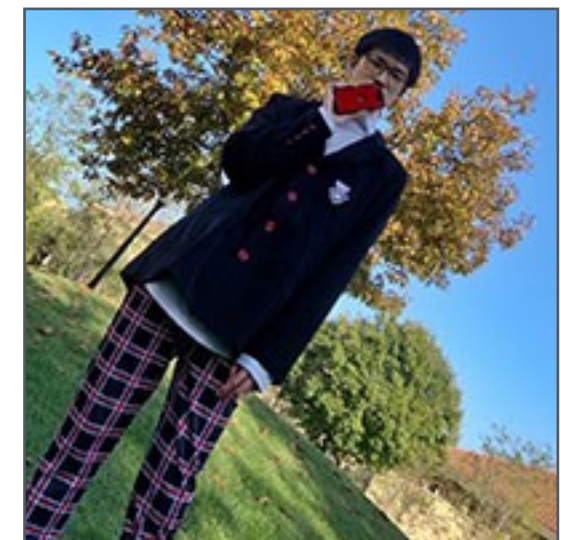


**Josephine  
the (Graphics) Cat**

**Kayvon Fatahalian**



**David  
Yao**



**Yinchen  
Xu**



**Wen  
Zhou**

# **Discussion:**

## **Why study computer graphics?**

# What is computer graphics?

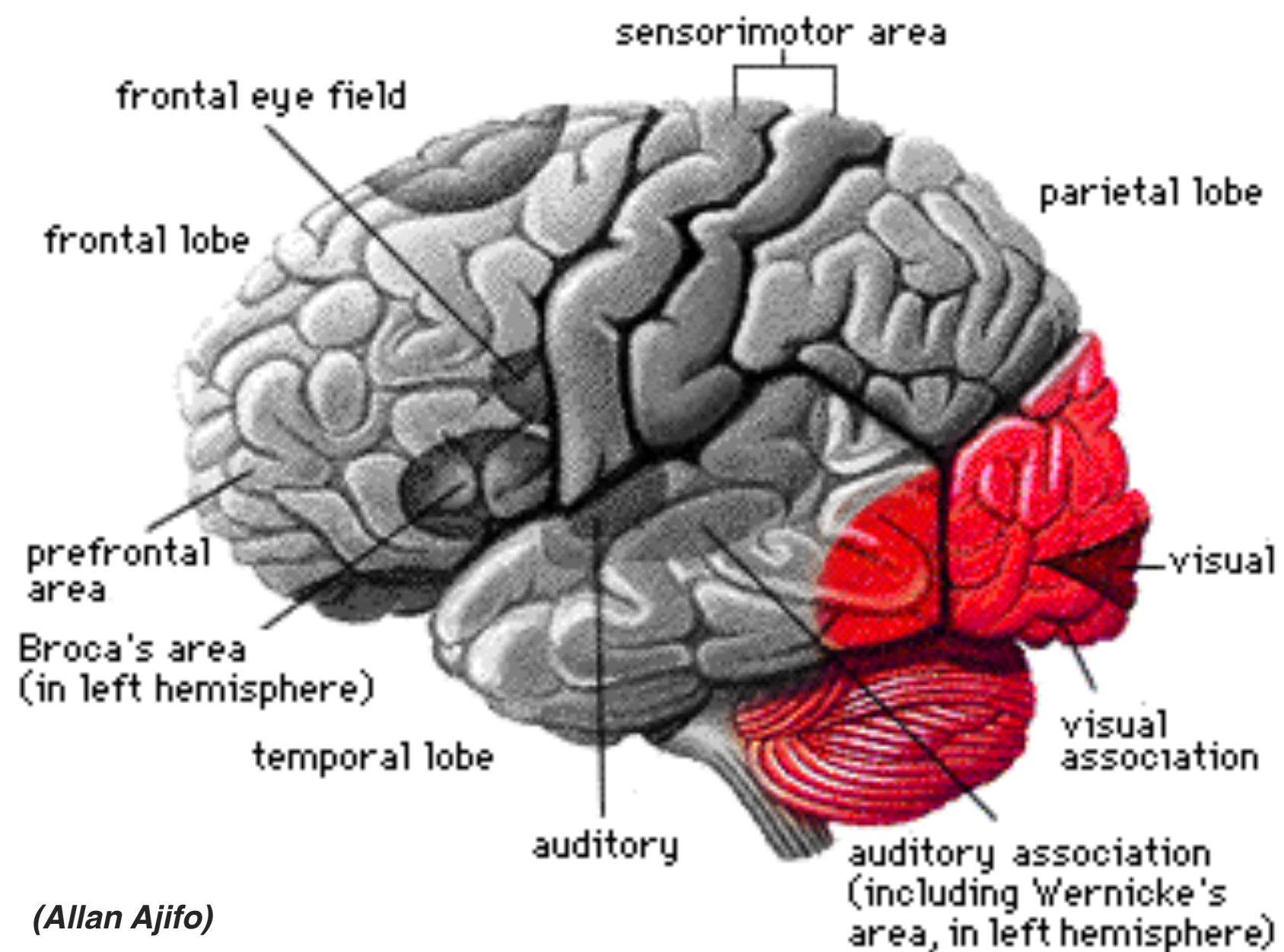
**com • put • er graph • ics** /kəm'pyʊədər 'ɡrafiks/ *n.*

The use of computers to synthesize and manipulate visual information.



# Why *visual* information?

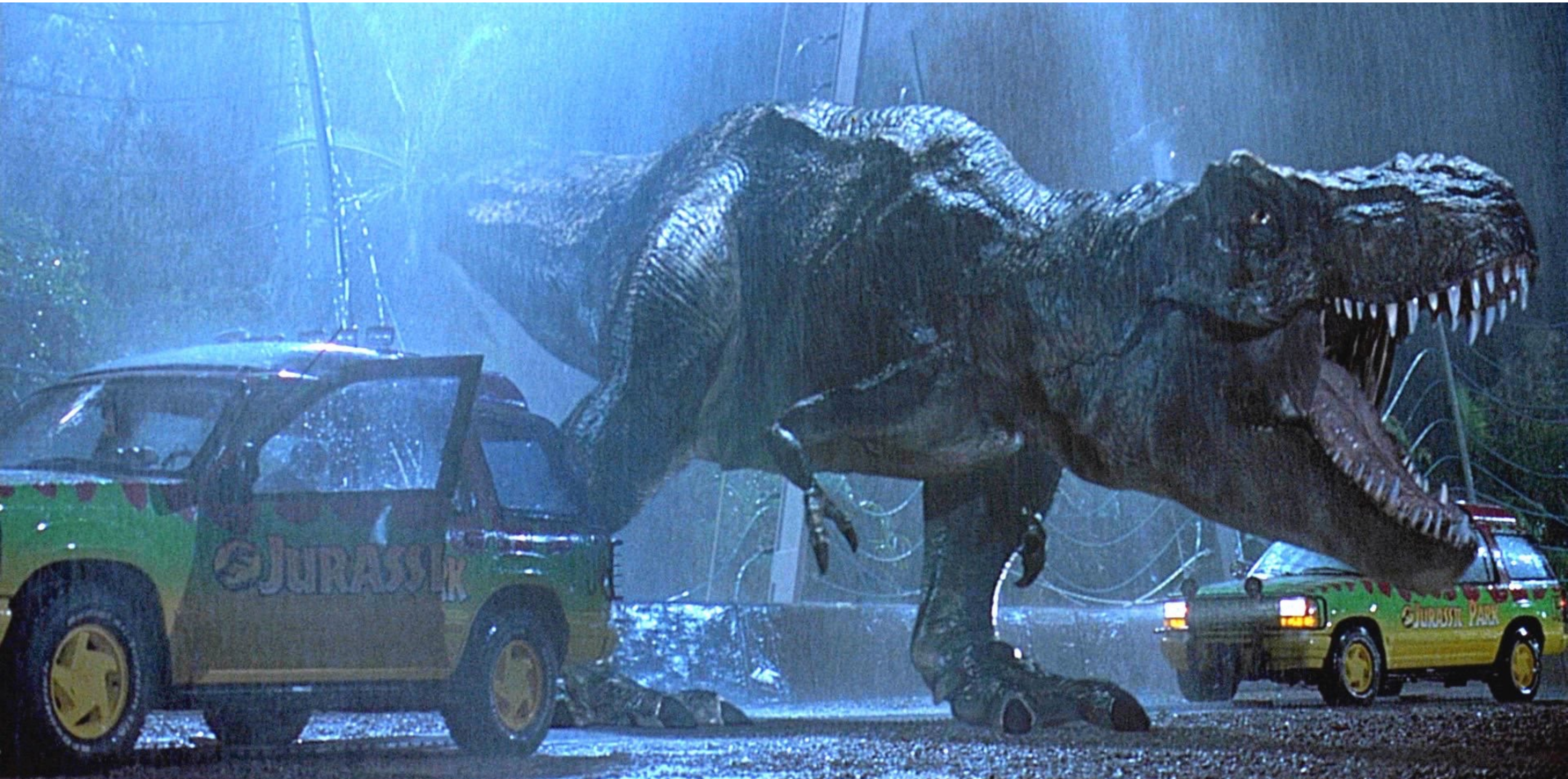
About 30% of brain dedicated to visual processing...



...eyes are highest-bandwidth port into the head!



# Movies



**Jurassic Park (1993)**



# Movies



**The Matrix (1999)**



# Computer games



Uncharted 4 (Naughty Dog, 2016)

**This image is rendered in real-time on a modern GPU**



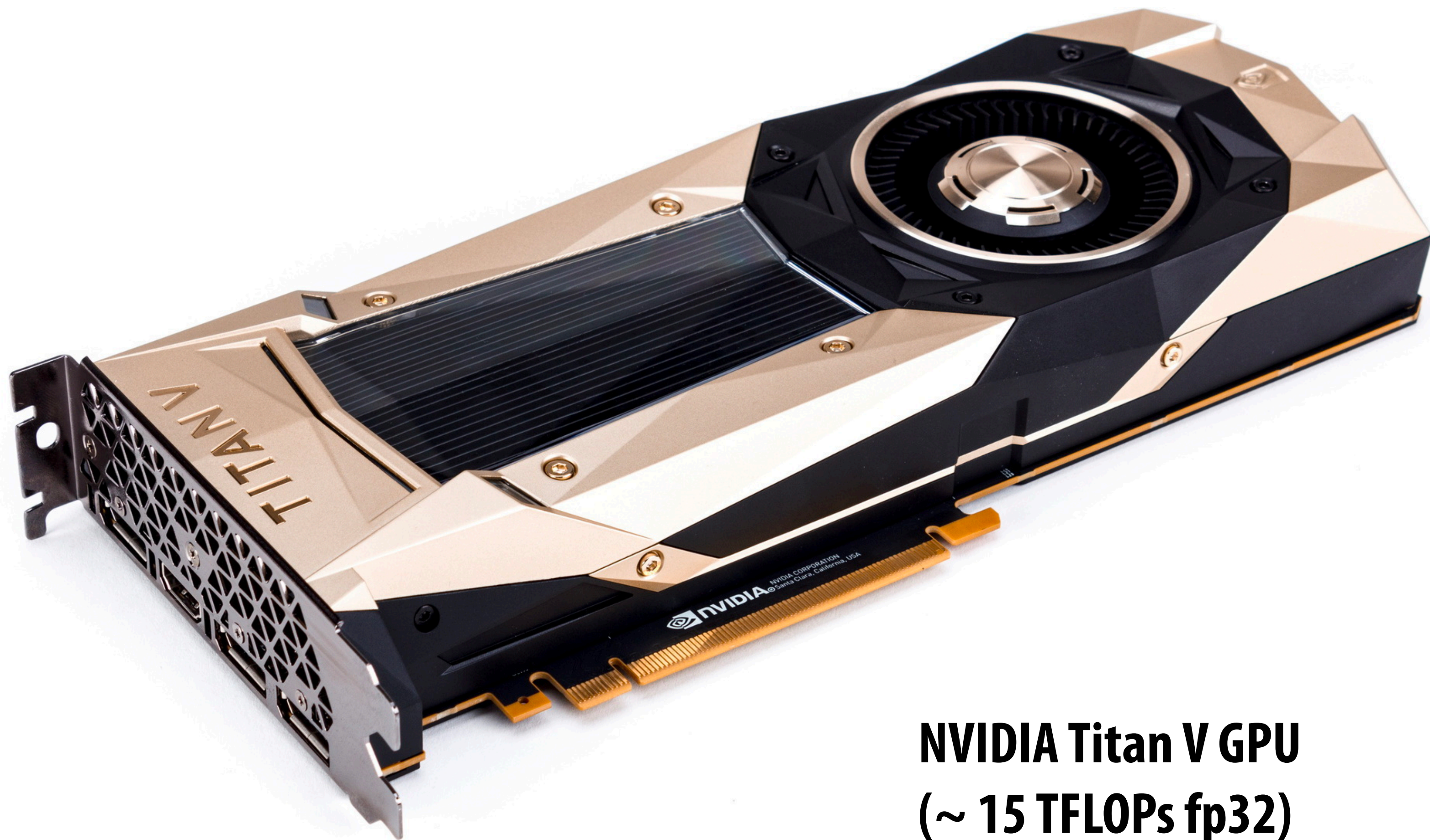
# Computer games



**Assassin's Creed Odyssey (Ubisoft 2018)**



# Supercomputing for games



**NVIDIA Titan V GPU**  
**(~ 15 TFLOPs fp32)**



# Virtual reality experiences





# Augmented reality



**Microsoft Hololens augmented reality headset concept**



# Illustration



**Indonesian cave painting (~38,000 BCE)**



# Digital illustration

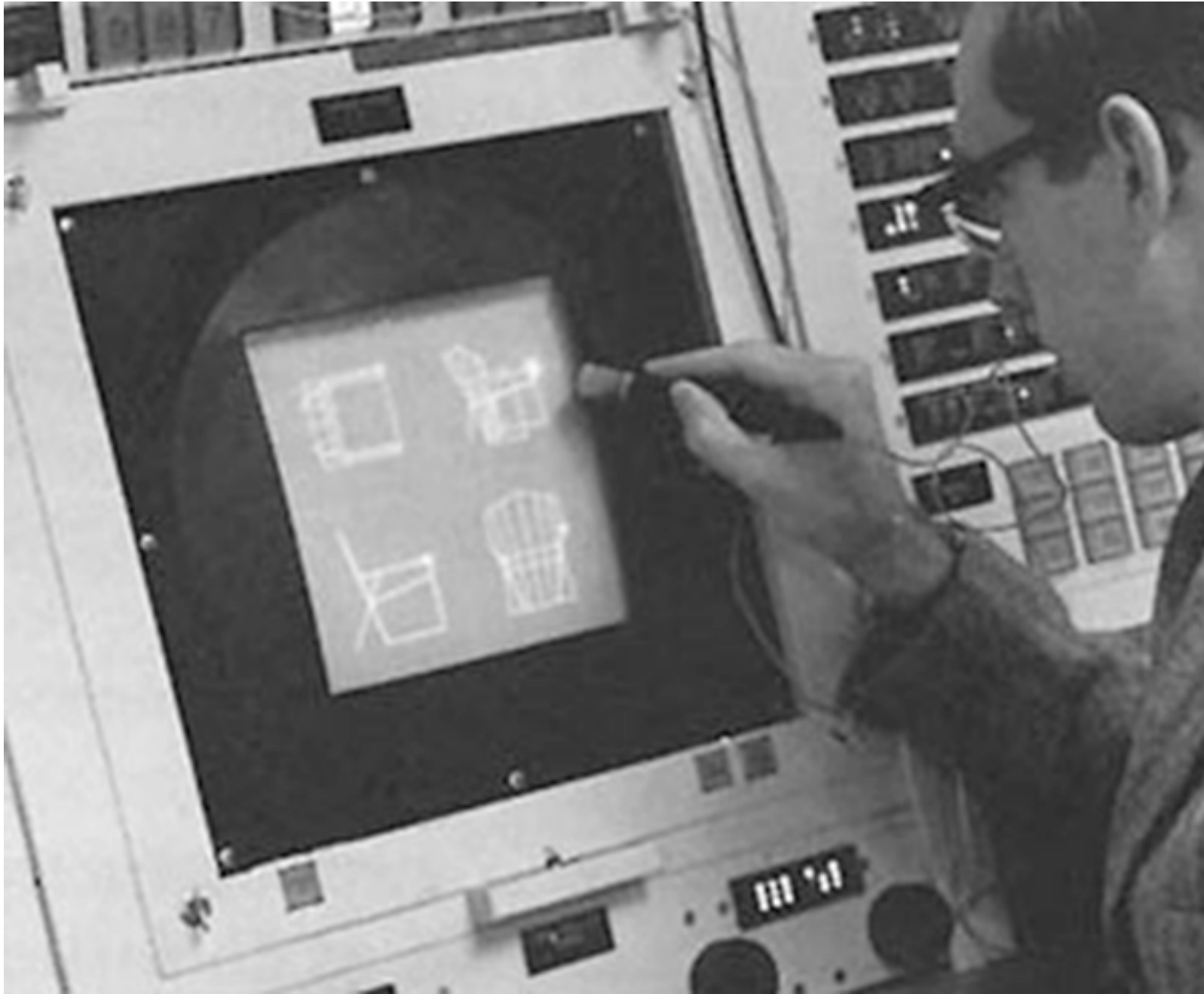


Meike Hakkart

<http://maquenda.deviantart.com/art/Lion-done-in-illustrator-327715059>



# Graphical user interfaces



**Ivan Sutherland, "Sketchpad" (1963)**



**Doug Engelbart  
Mouse**



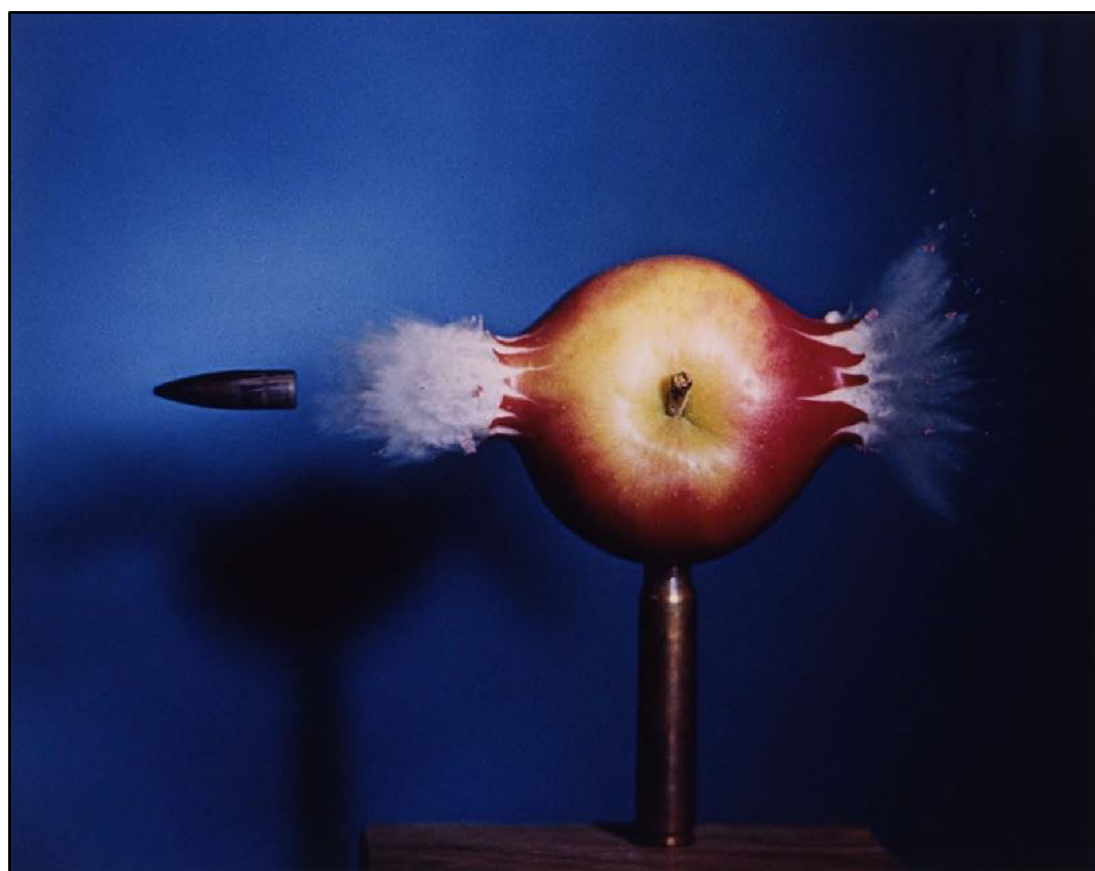
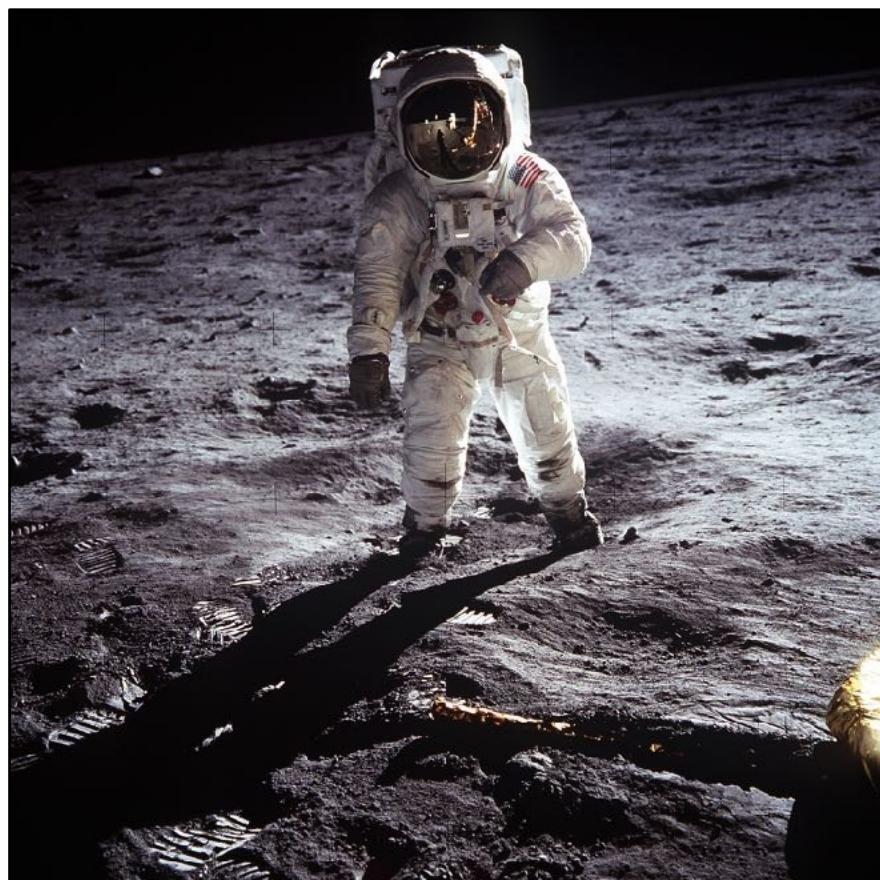
# Modern graphical user interfaces



**2D drawing and animation are ubiquitous in computing.  
Typography, icons, images, transitions, transparency, ...  
(all rendered at high frame rate for rich experience)**



# Digital photography



NASA | Walter looss | Steve McCurry  
Harold Edgerton | NASA | National Geographic



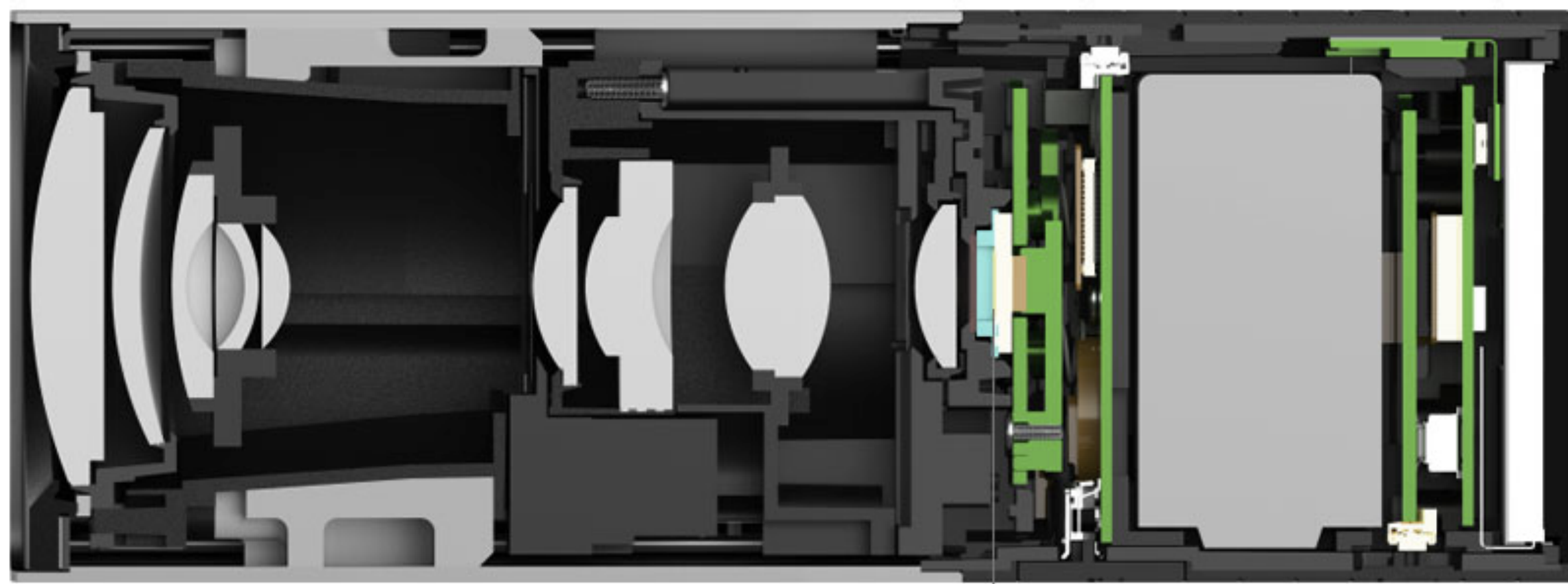
# Ubiquitous imaging



**Cameras everywhere**



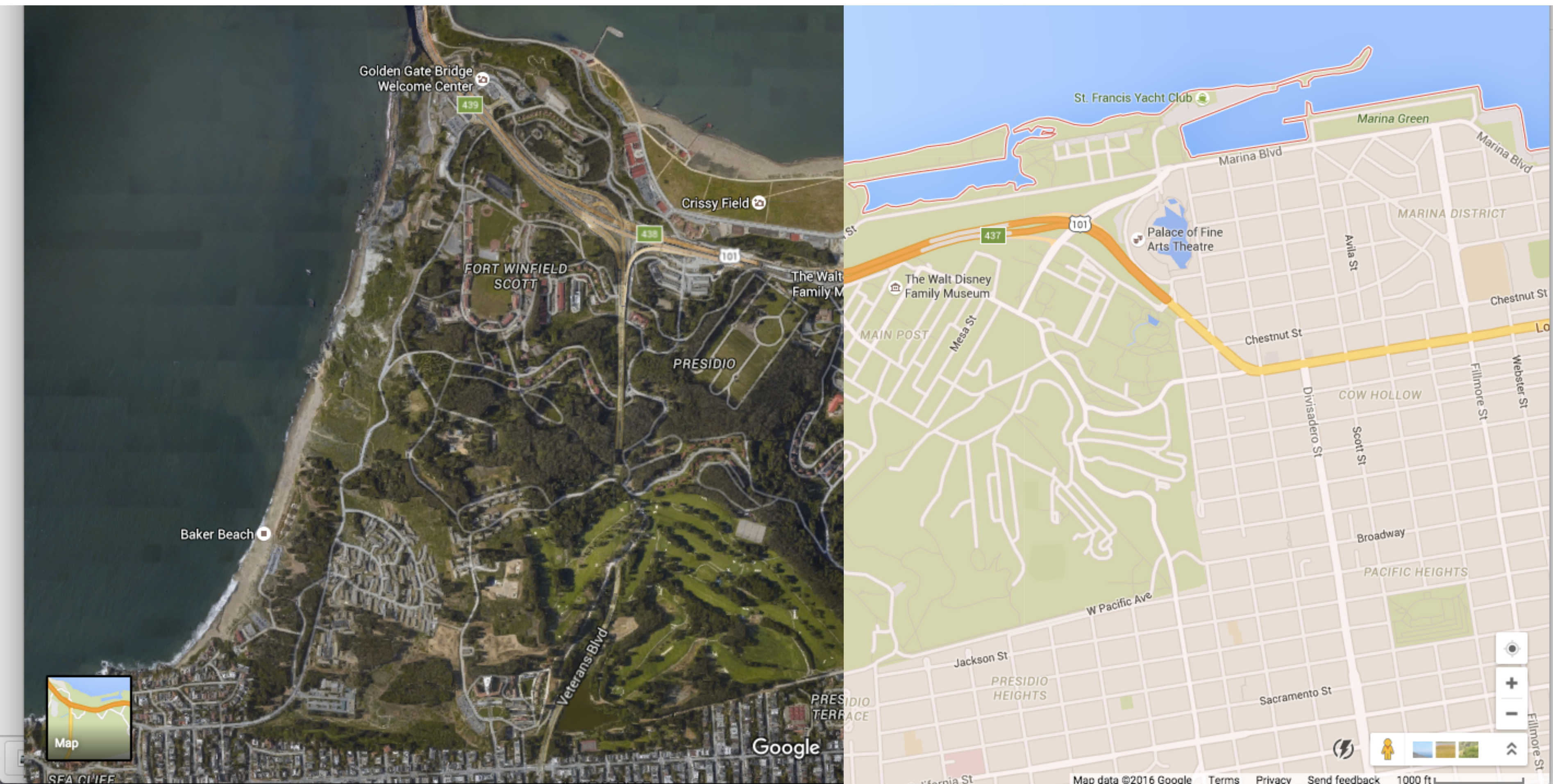
# Computational cameras



**Panaromic stitching, HDR photos, light field cameras, ...**



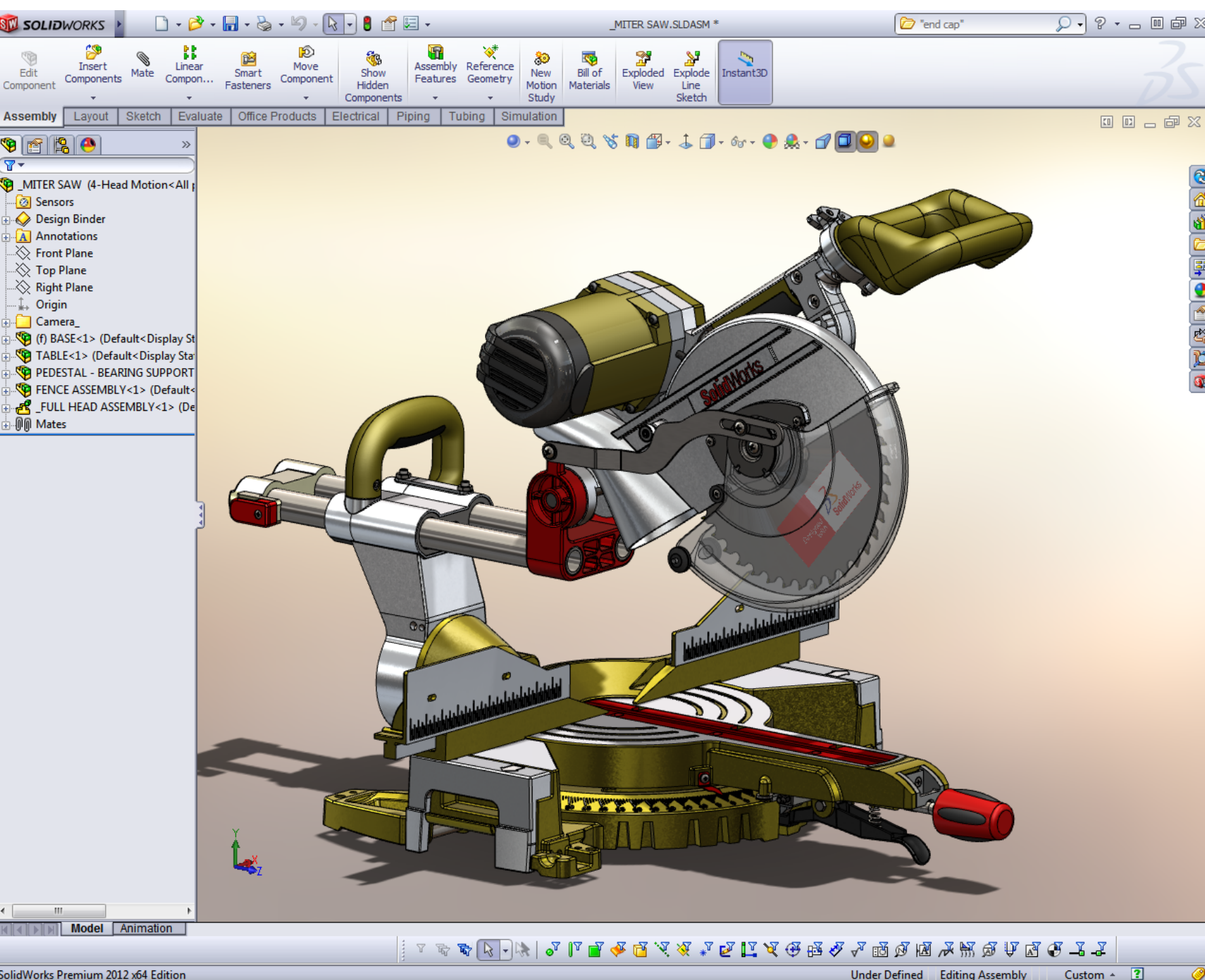
# Imaging for mapping



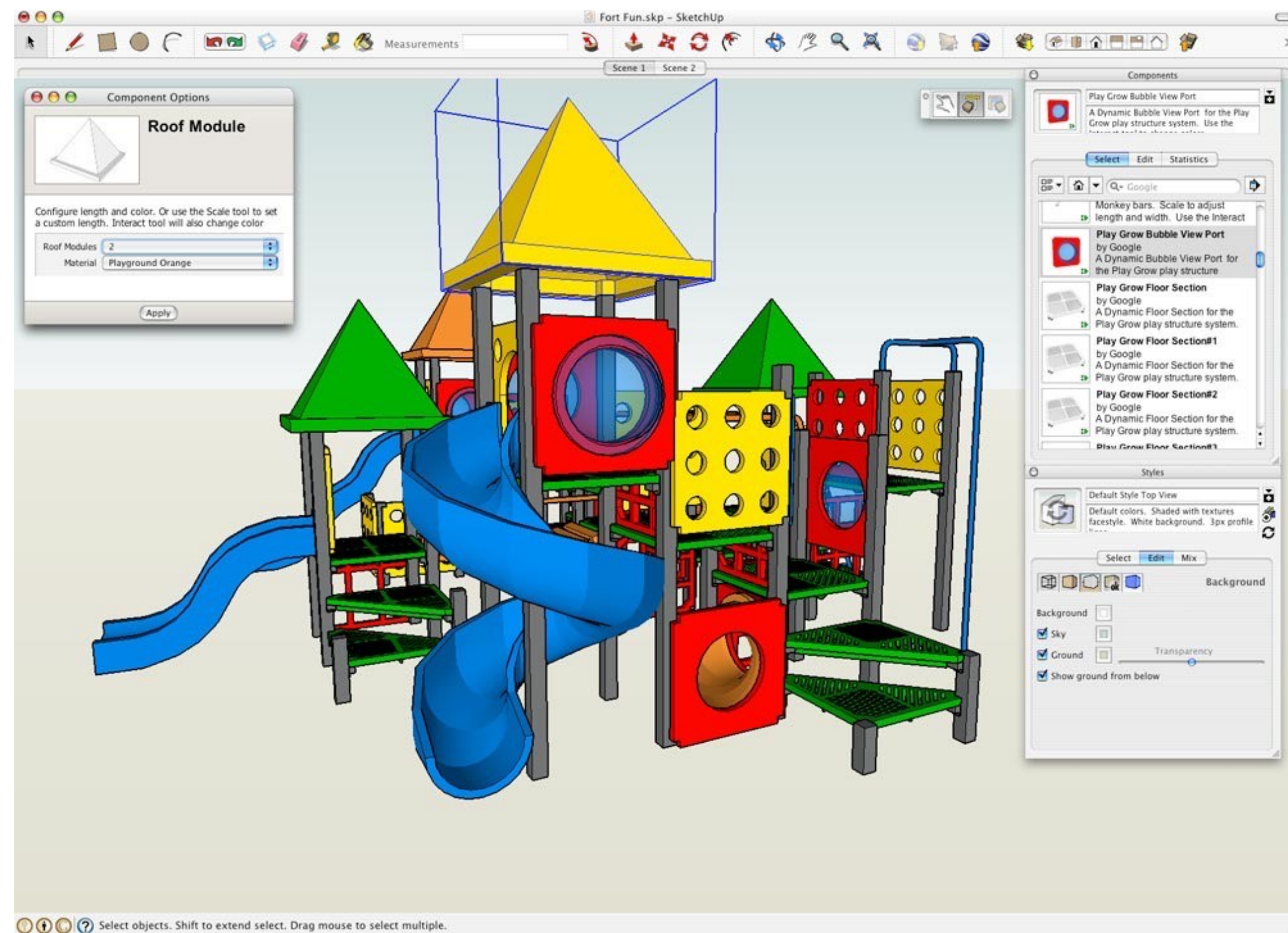
**Maps, satellite imagery, street-level imaging,...**



# Computer aided design



**SolidWorks**



**SketchUp**

**For mechanical, architectural, electronic, optical, ...**



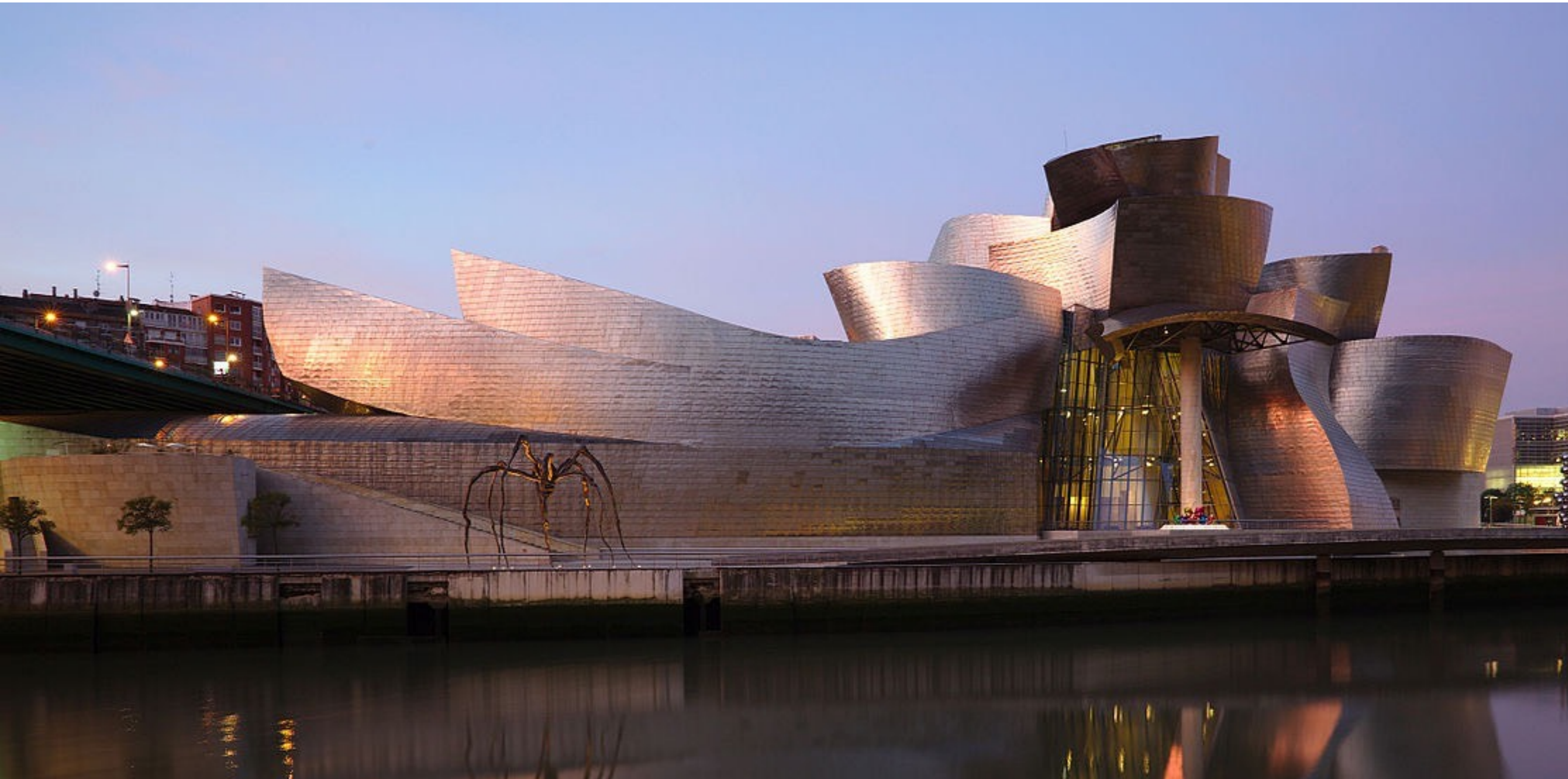
# Product design and visualization



**Ikea - 75% of catalog is rendered imagery**



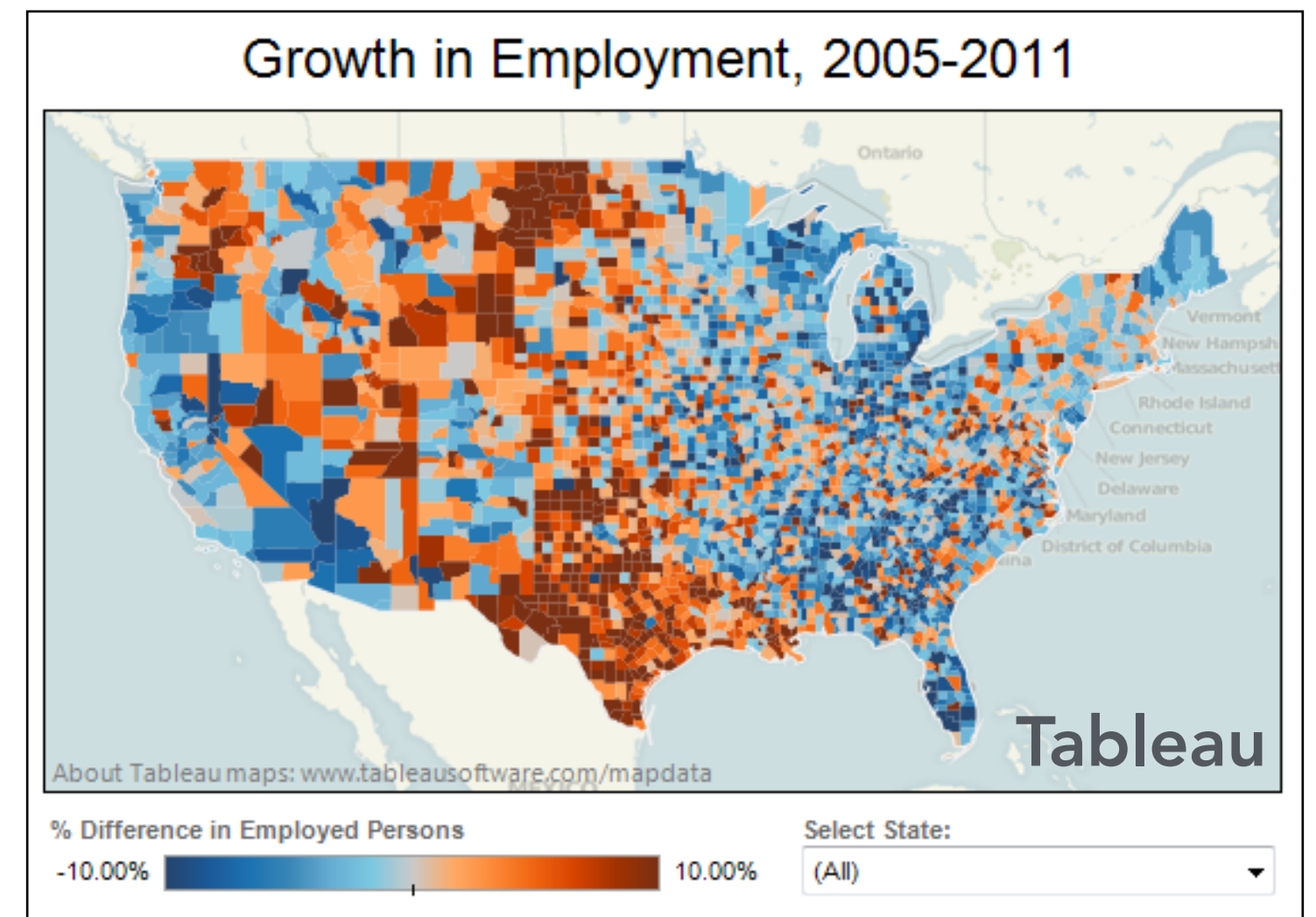
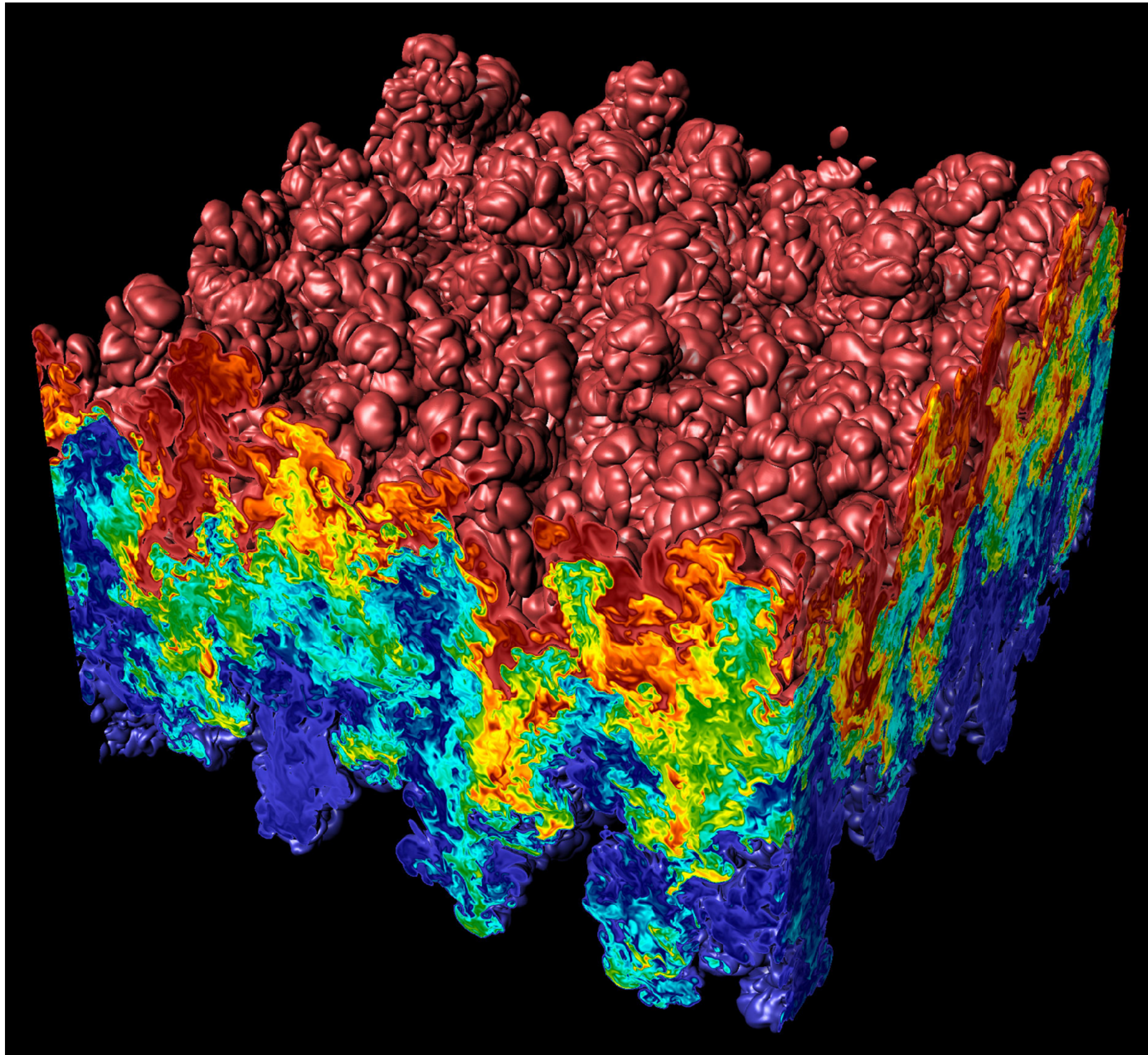
# Architectural design



**Bilbao Guggenheim, Frank Gehry**



# Visualization



**Science, engineering, medicine, journalism, ...**



# Simulation



**Driving simulator  
Toyota Higashifuji Technical Center**

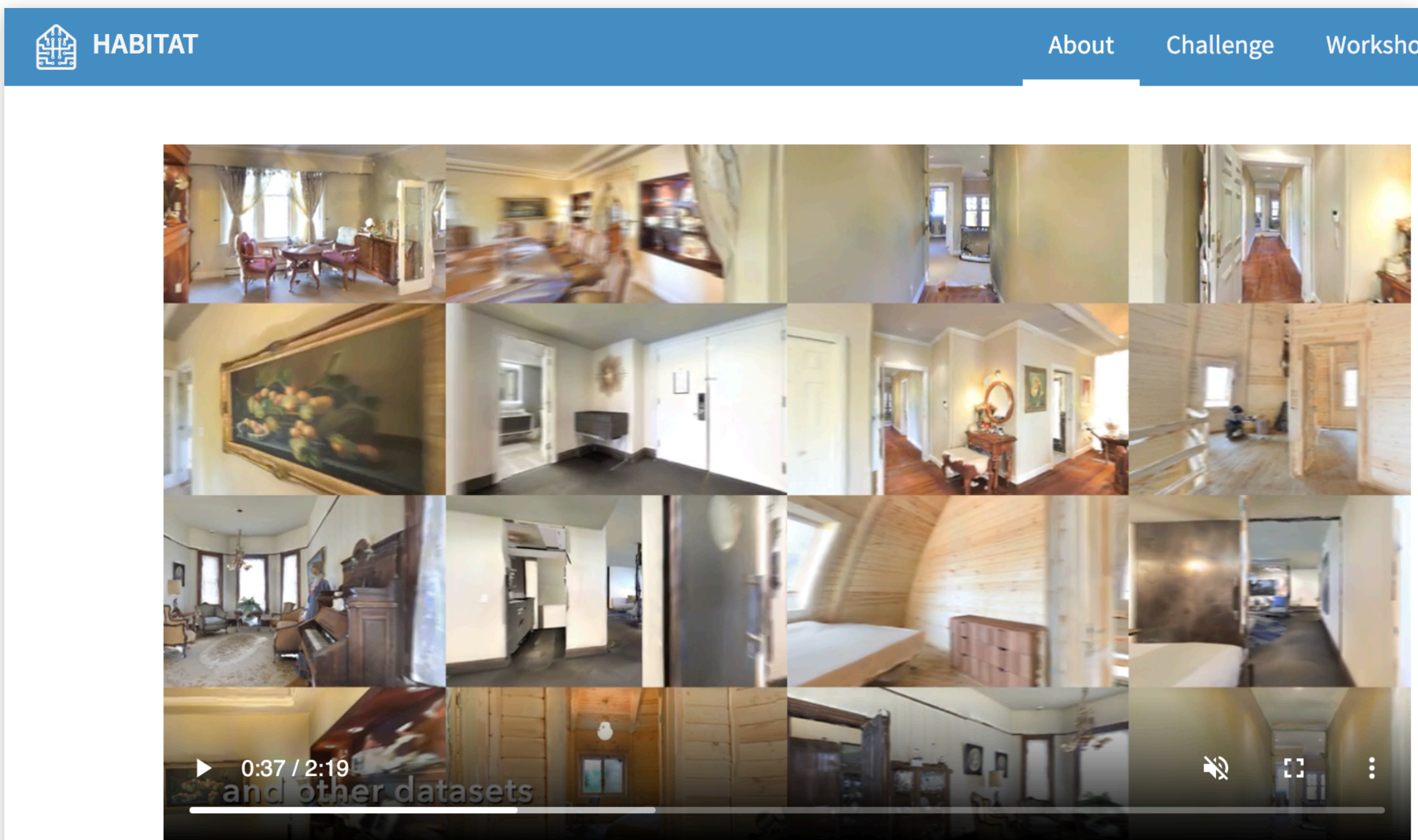


**da Vinci surgical robot  
Intuitive Surgical**

**Flight simulator, driving simulator, surgical simulator, ...**



# Simulation for training models



**AI Habitat:**  
simulator for training AI agents

**Carla:**  
autonomous driving simulator

AI Habitat enables training of embodied AI agents (virtual robots) in a simulated environment before transferring the learned skills to reality. This empowers a paradigm shift from static datasets (e.g. ImageNet, COCO, VQA) to embodied AI where agents act in a dynamic environment for active perception, long-term planning, learning from interaction, and decision-making.

**Why the name *Habitat*?** Because that's where AI agents live 😊

Habitat is a platform for embodied AI research that consists of [Habitat-Sim](#) and [Habitat-Lab](#).

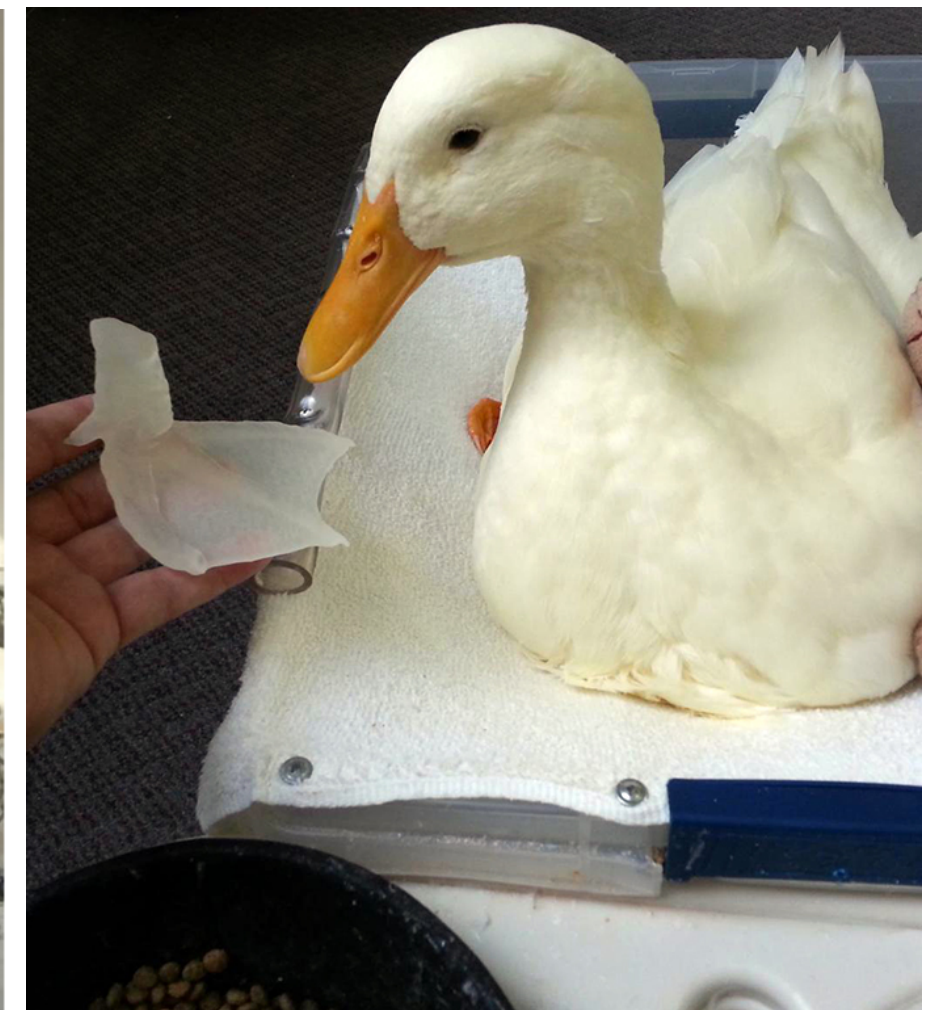
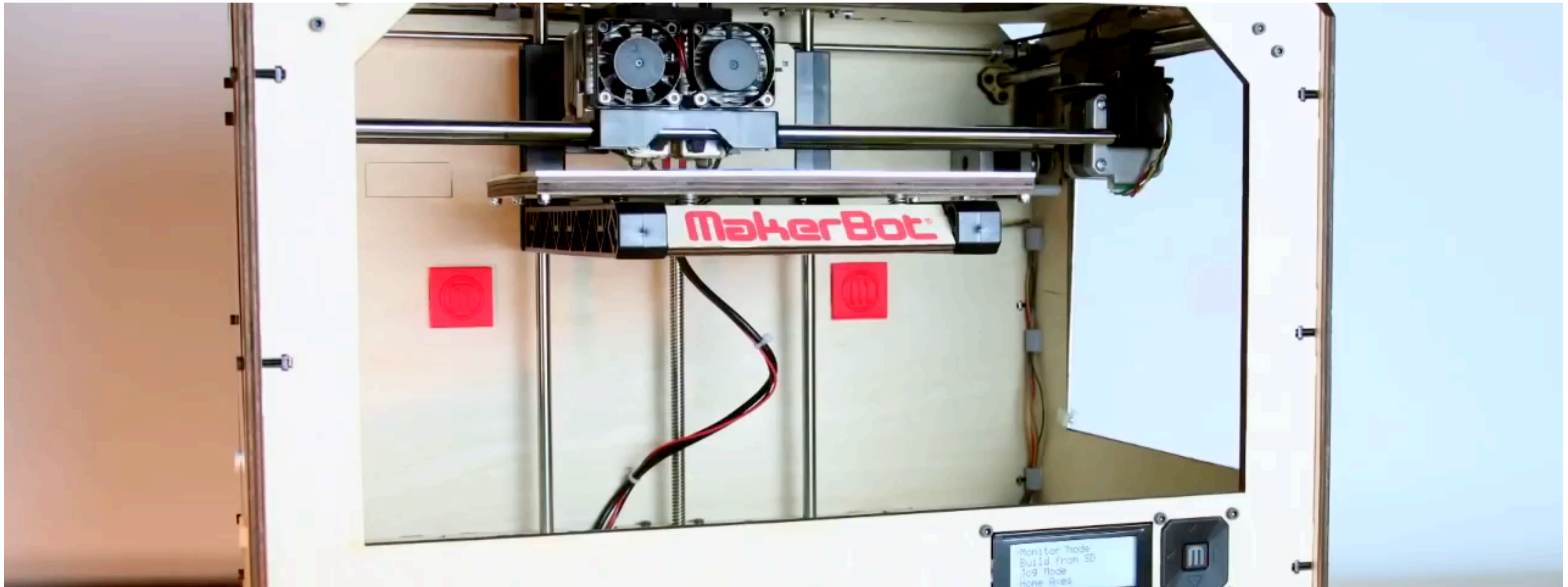
## Habitat-Sim

A flexible, high-performance 3D simulator with configurable agents and environments. It supports built-in support for [MatterPort3D](#), [Gibson](#), [Replica](#), and [ScanNet](#). The MatterPort3D dataset, Habitat Sim achieves several thousand frames per second.





# 3D fabrication





# Foundations of computer graphics

- All these applications demand *sophisticated* theory and systems
- Science and mathematics
  - Physics of light, color, optics
  - Math of curves, surfaces, geometry, perspective, ...
  - Sampling
- Systems
  - Parallel, heterogeneous processing
  - Graphics-specific programming systems
  - Input/output devices
- Art and psychology
  - Perception: color, stereo, motion, image quality, ...
  - Art and design: composition, form, lighting, ...

# ACTIVITY: modeling and drawing a cube

- Goal: generate a realistic drawing of a cube
- Key questions:
  - *Modeling*: how do we describe the cube?
  - *Rendering*: how do we then visualize this model?



# ACTIVITY: modeling the cube

## ■ Suppose our cube is...

- centered at the origin  $(0,0,0)$
- has dimensions  $2 \times 2 \times 2$

## ■ QUESTION: What are the coordinates of the cube vertices?

A: $(1, 1, 1)$	E: $(1, 1, -1)$
B: $(-1, 1, 1)$	F: $(-1, 1, -1)$
C: $(1, -1, 1)$	G: $(1, -1, -1)$
D: $(-1, -1, 1)$	H: $(-1, -1, -1)$

## ■ QUESTION: What about the edges?

AB, CD, EF, GH,  
AC, BD, EG, FH,  
AE, CG, BF, DH

# ACTIVITY: drawing the cube

## ■ Now have a digital description of the cube:

### VERTICES

A: ( 1, 1, 1 )	E: ( 1, 1, -1 )
B: ( -1, 1, 1 )	F: ( -1, 1, -1 )
C: ( 1, -1, 1 )	G: ( 1, -1, -1 )
D: ( -1, -1, 1 )	H: ( -1, -1, -1 )

### EDGES

AB, CD, EF, GH,  
AC, BD, EG, FH,  
AE, CG, BF, DH

## ■ How do we draw this 3D cube as a 2D (flat) image?

## ■ Basic strategy:

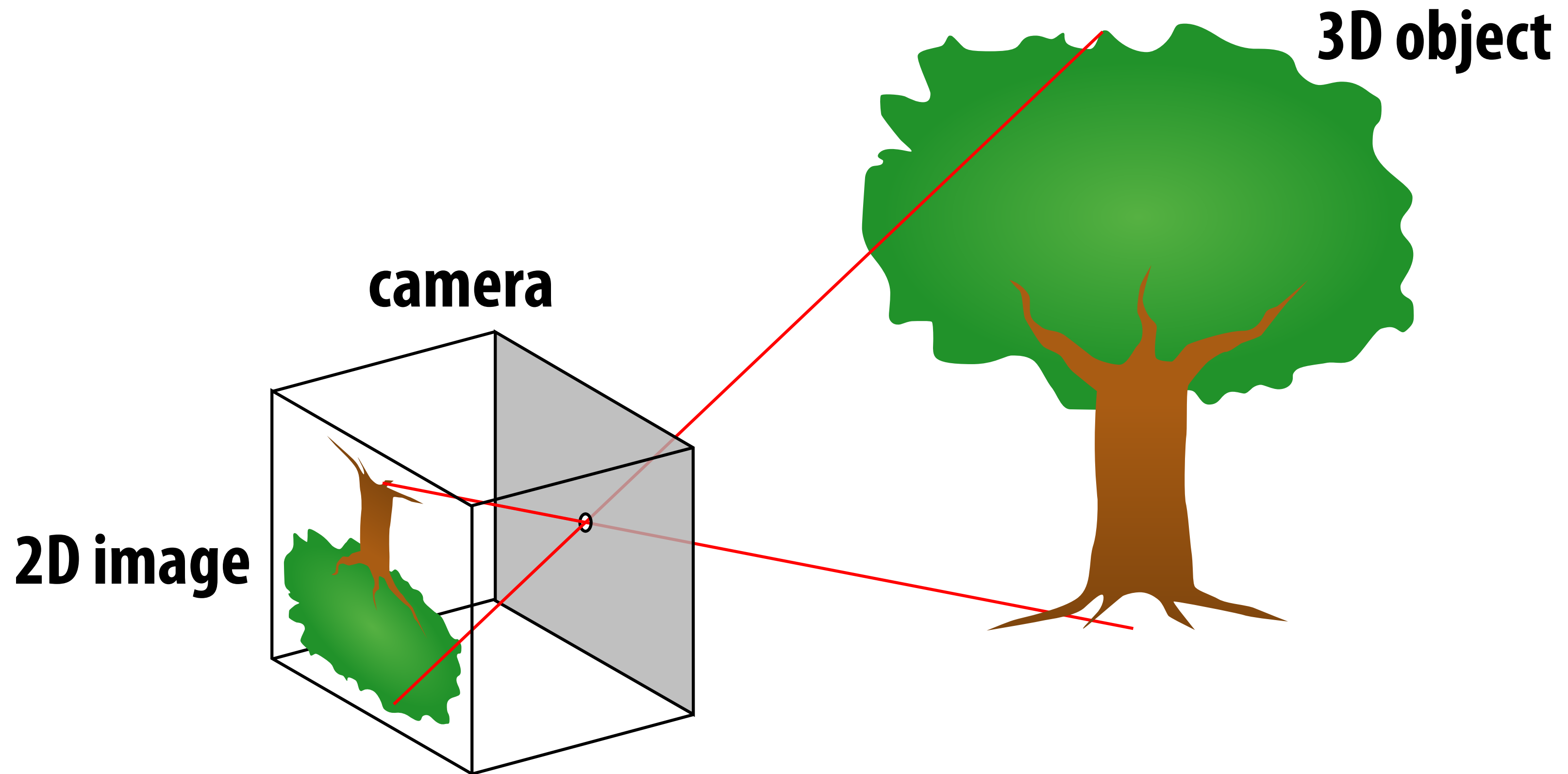
1. Project 3D vertices to 2D points in the image

2. Connect 2D points with straight lines

## ■ ...Ok, but how?

# Perspective projection

- Objects look smaller as they get further away (“perspective”)
- Why does this happen?
- Consider simple (“pinhole”) model of a camera:





# For those that didn't do this in grade school

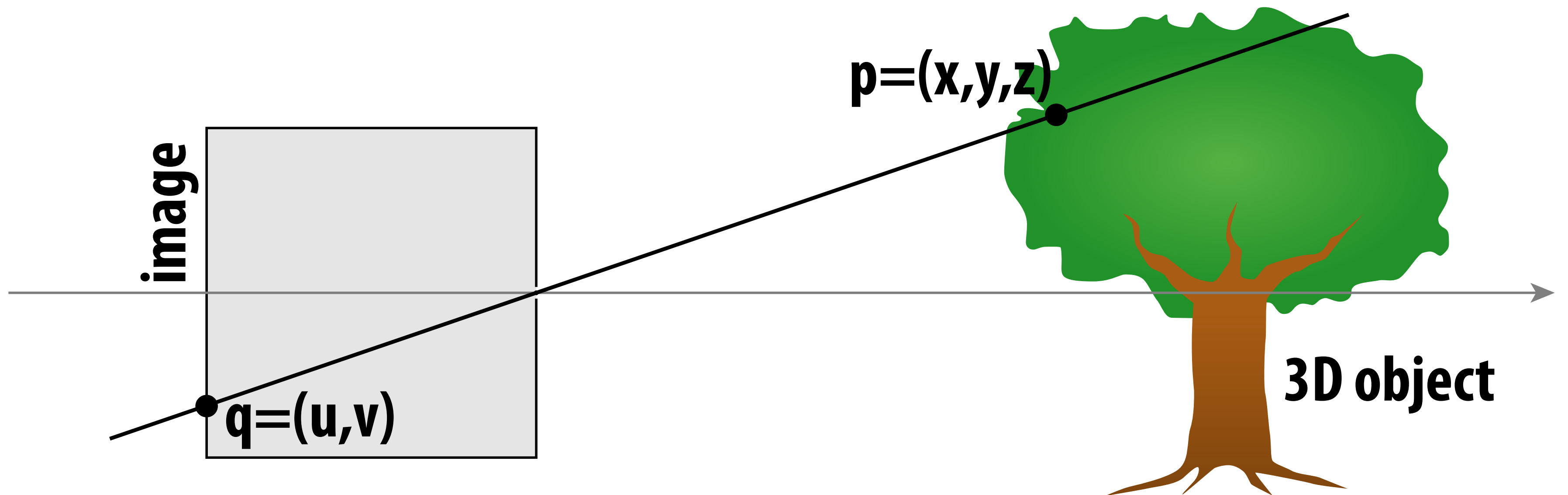


<http://jdaniel4smom.com/2017/06/pinhole-camera.html>



# Perspective projection: side view

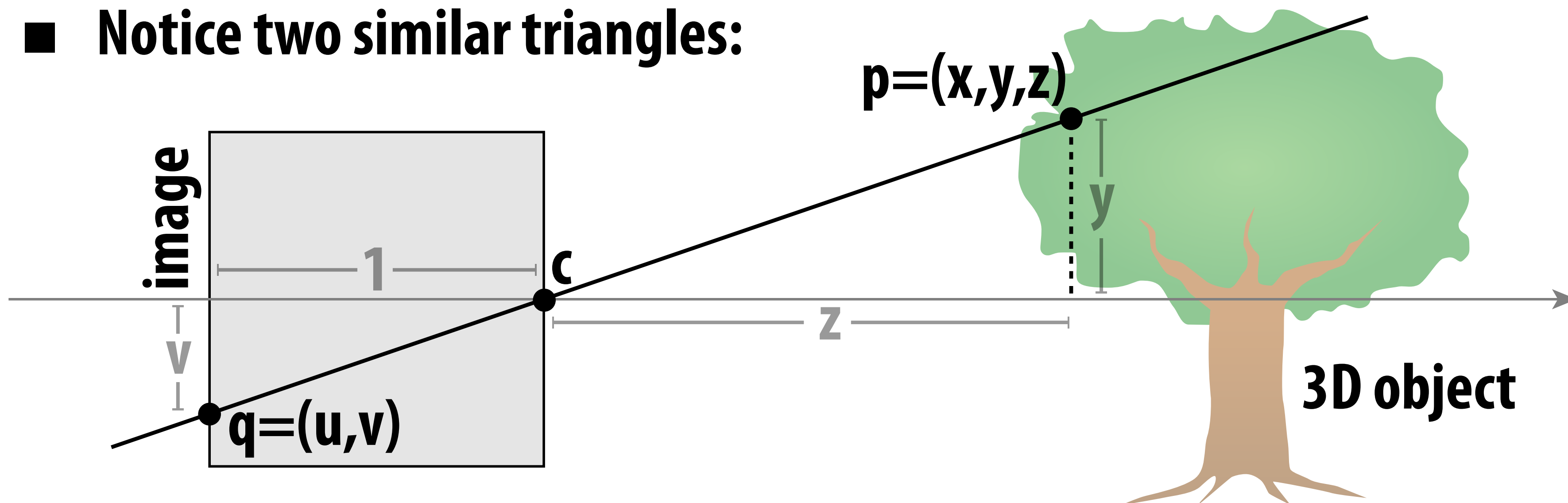
- Where exactly does a point  $p = (x, y, z)$  end up on the image?
- Let's call the image point  $q = (u, v)$





# Perspective projection: side view

- Where exactly does a point  $p = (x, y, z)$  end up on the image?
- Let's call the image point  $q = (u, v)$
- Notice two similar triangles:



- Assume camera has unit size, coordinates relative to pinhole  $c$
- Then  $v/1 = y/z$ , i.e., vertical coordinate is just the slope  $y/z$
- Likewise, horizontal coordinate is  $u = x/z$



# ACTIVITY: now draw image made by pinhole camera

## ■ Need 12 volunteers

- each person will draw one cube edge
- assume camera is at point  $c=(2,3,5)$
- convert  $(X,Y,Z)$  of both endpoints of edge to  $(u,v)$ :
  1. subtract camera  $c$  from vertex  $(X,Y,Z)$  to get  $(x,y,z)$
  2. divide  $x$  and  $y$  by  $z$  to get  $(u,v)$ —*write as a fraction*
- draw line between  $(u1,v1)$  and  $(u2,v2)$

### VERTICES

A: ( 1, 1, 1 )	E: ( 1, 1, -1 )
B: ( -1, 1, 1 )	F: ( -1, 1, -1 )
C: ( 1, -1, 1 )	G: ( 1, -1, -1 )
D: ( -1, -1, 1 )	H: ( -1, -1, -1 )

### EDGES

AB, CD, EF, GH,  
AC, BD, EG, FH,  
AE, CG, BF, DH



# ACTIVITY: how did we do? \*

## 2D coordinates:

A:  $(1/4, 1/2)$

B:  $(3/4, 1/2)$

C:  $(1/4, 1)$

D:  $(3/4, 1)$

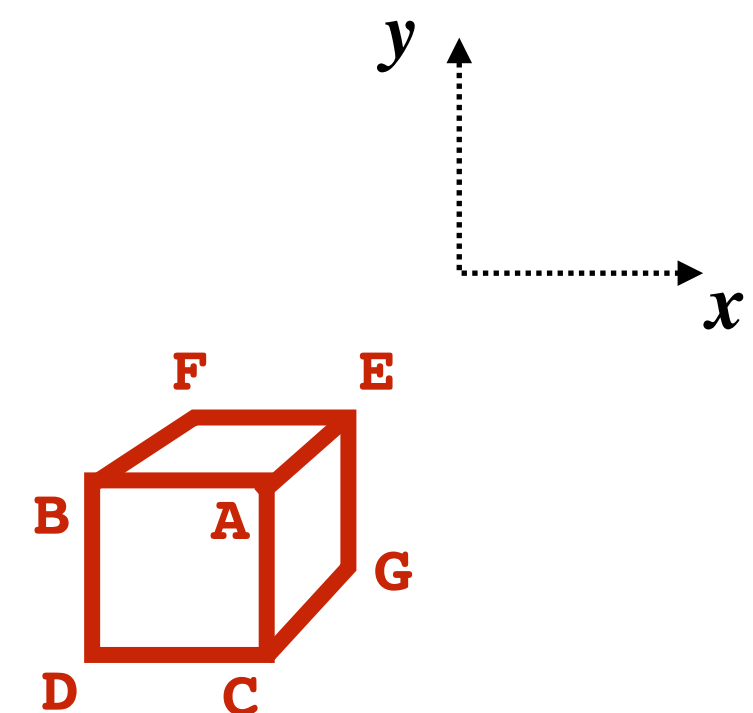
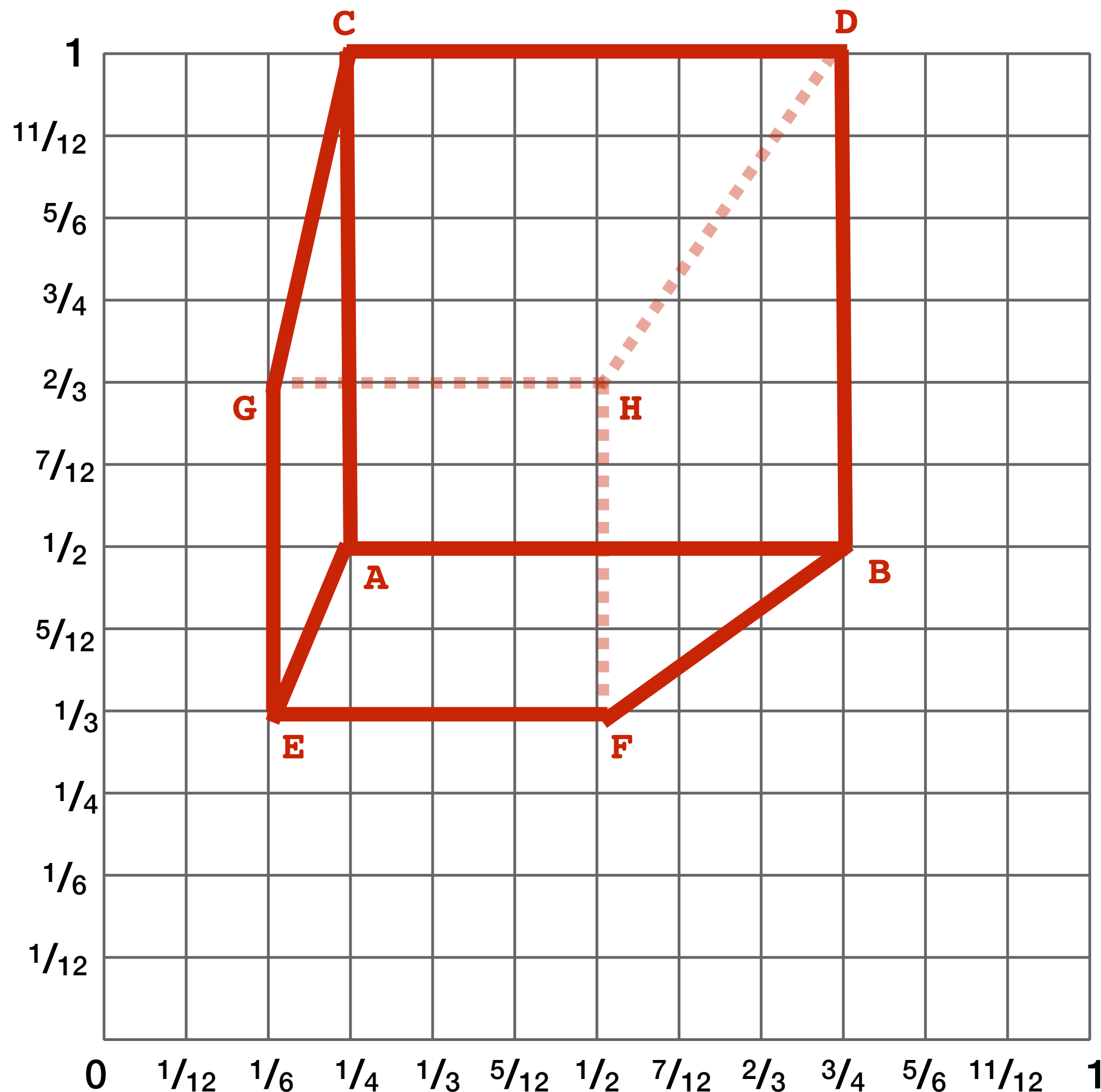
E:  $(1/6, 1/3)$

F:  $(1/2, 1/3)$

G:  $(1/6, 2/3)$

H:  $(1/2, 2/3)$

\* keep in mind, this image is mirrored since it is a pinhole projection. Mirror the result and you get...



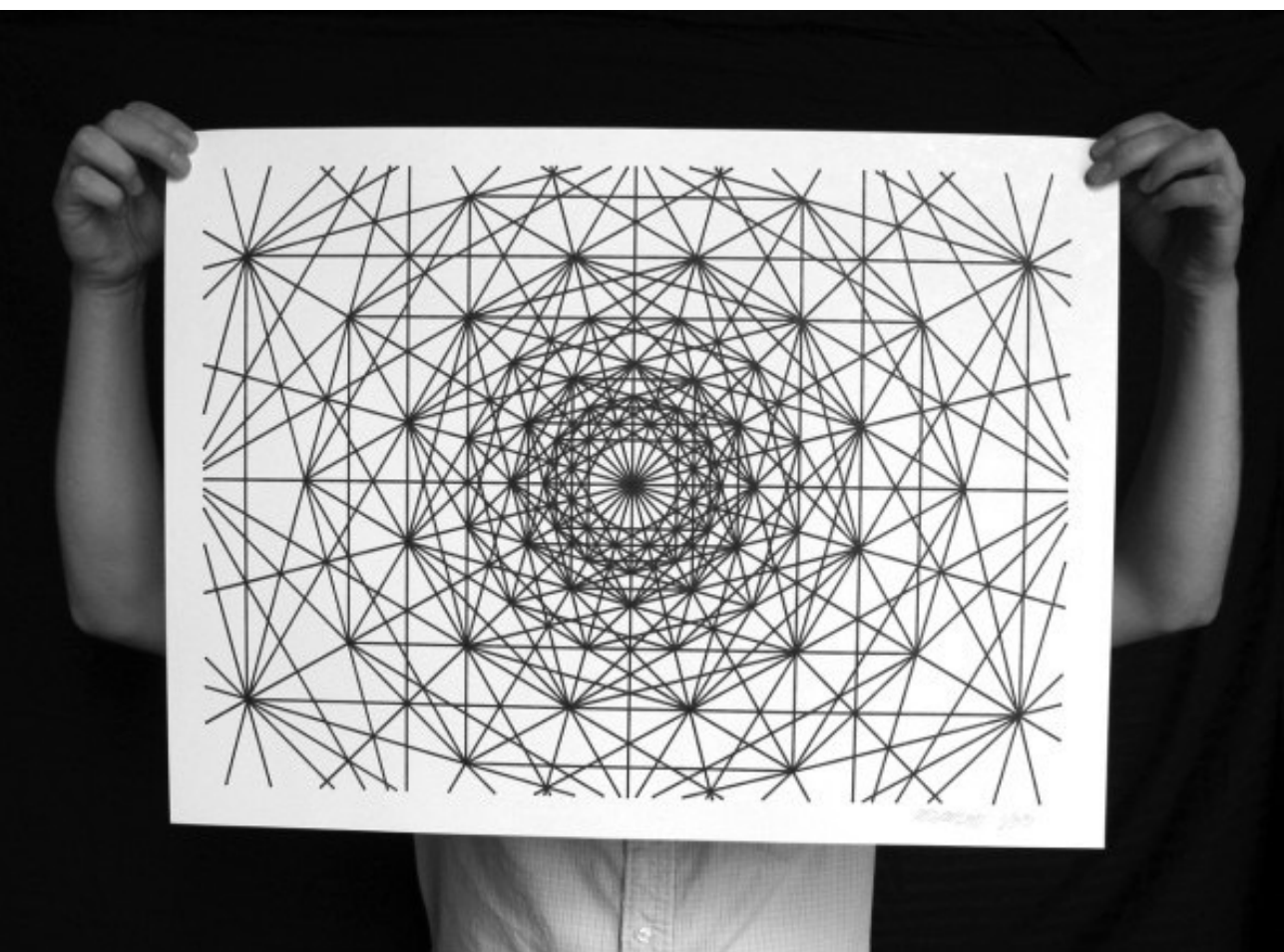
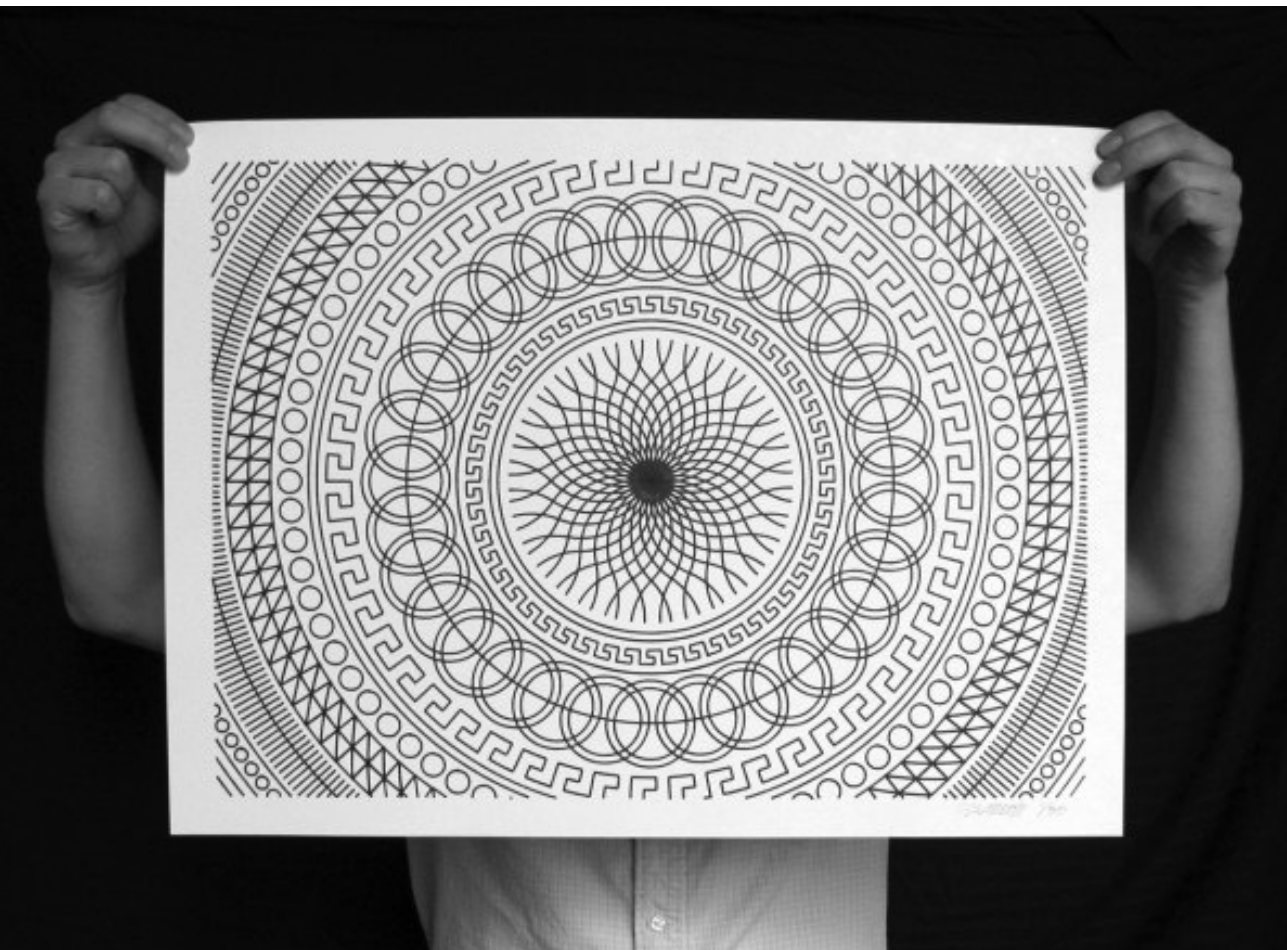


**But wait...**

**How do we draw lines on a computer?**



# CNC sharpie drawing machine ;-)



<http://44rn.com/projects/numerically-controlled-poster-series-with-matt-w-moore/>

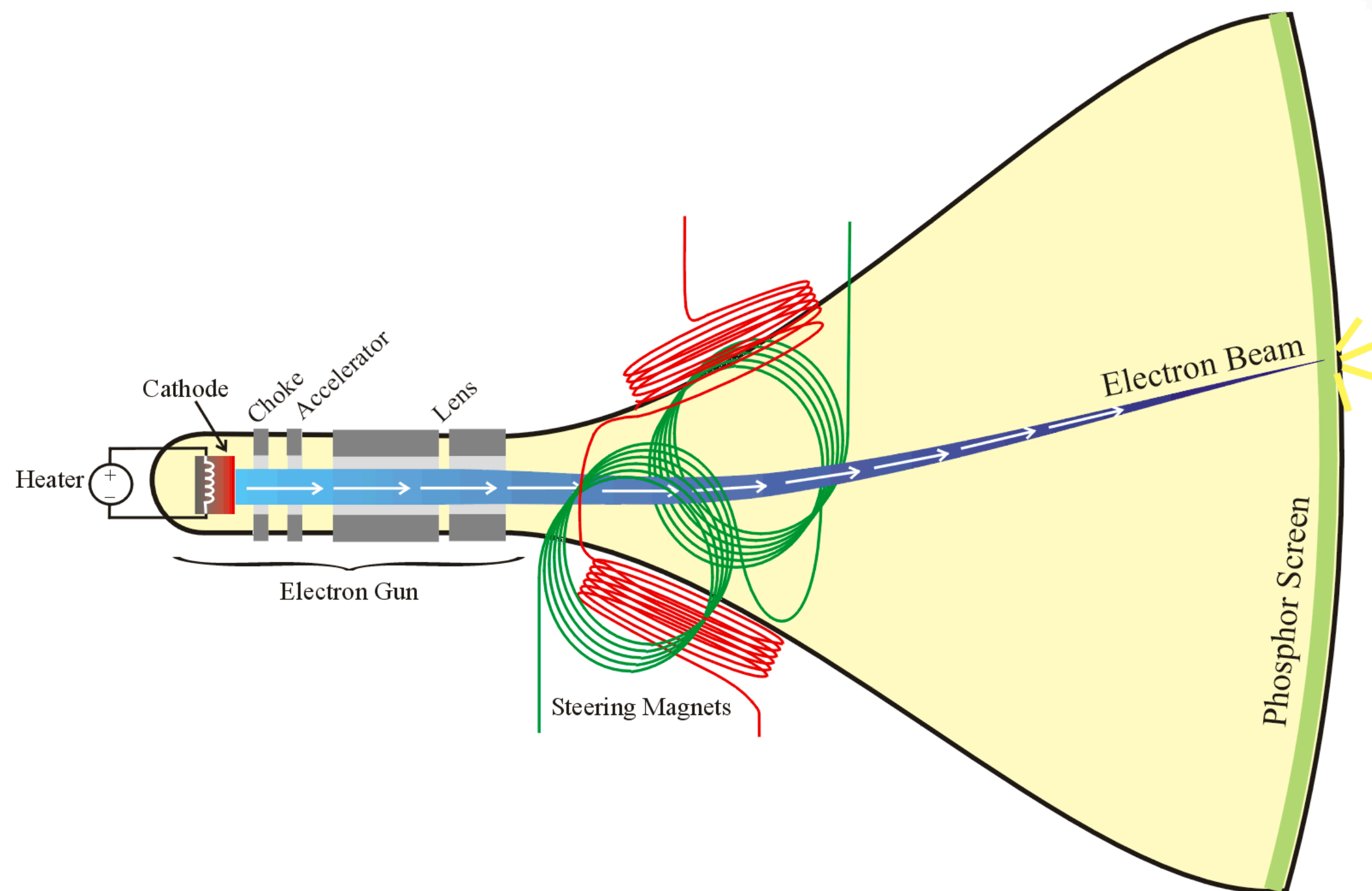


# Oscilloscope



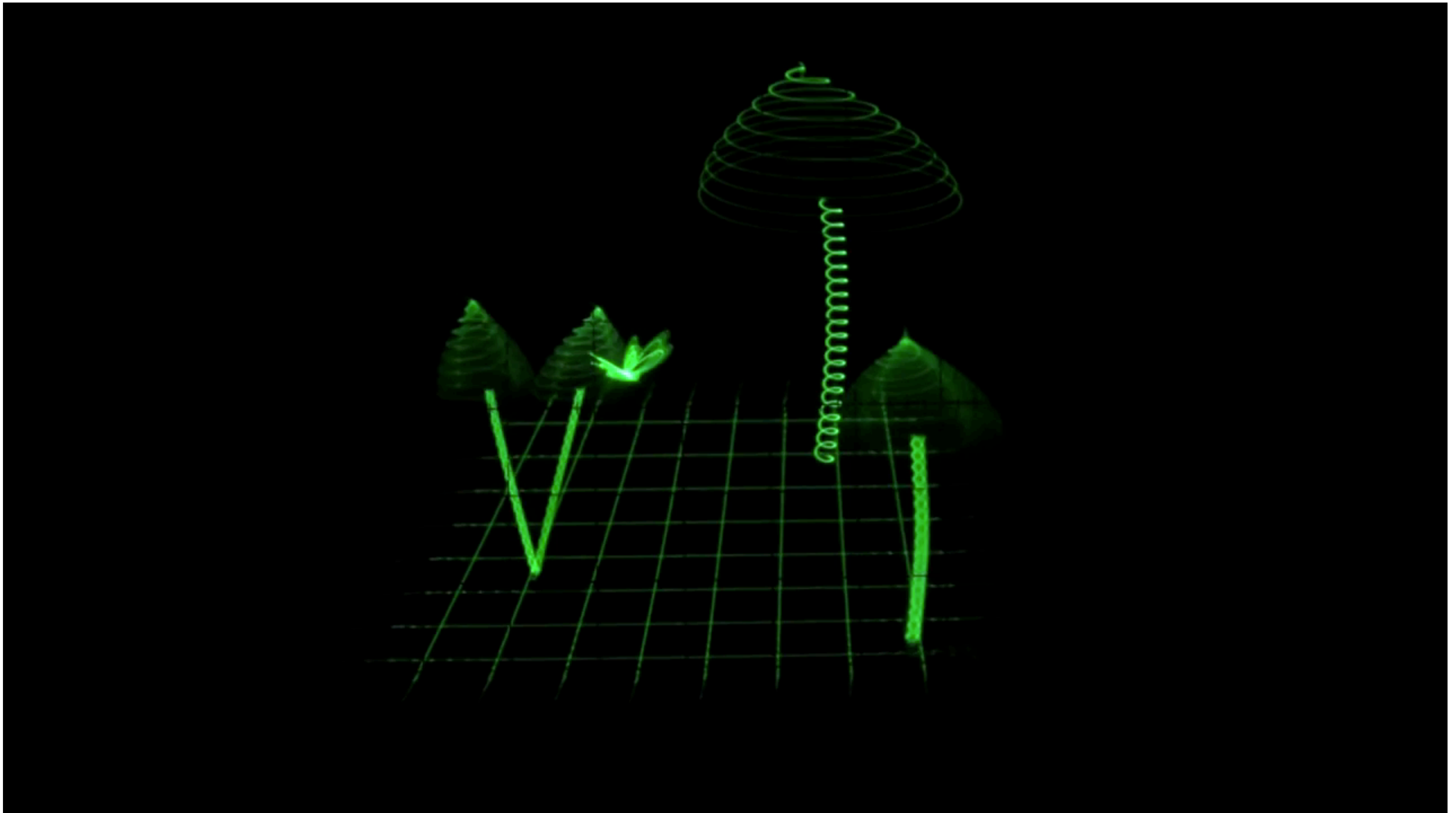


# Cathode ray tube





# Oscilloscope art :-)



<https://www.youtube.com/watch?v=rtR63-ecUNo>



# Frame buffer: memory for a raster display

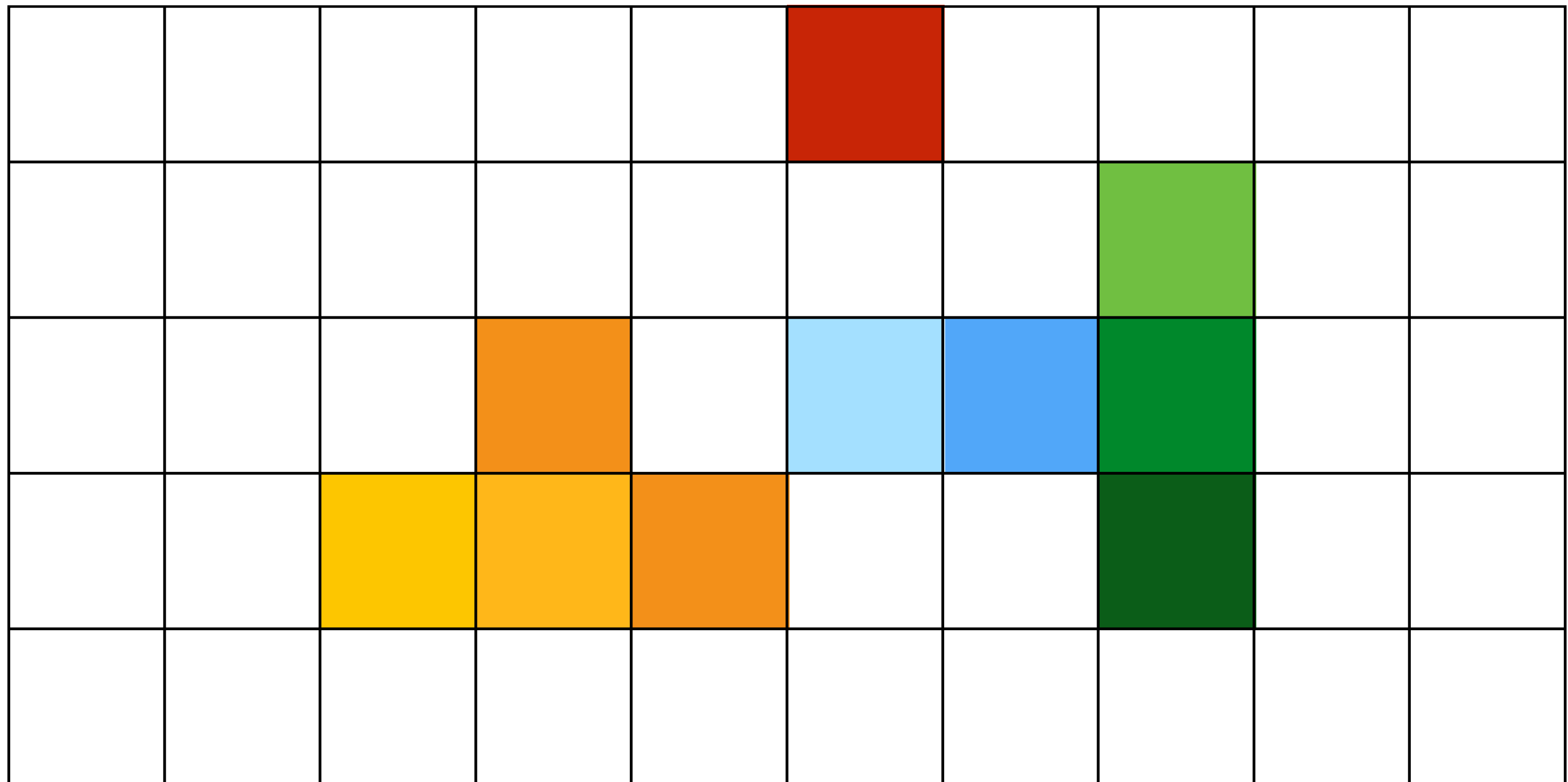


image = “2D array of colors”



# Output for a raster display

- **Common abstraction of a raster display:**
  - **Image represented as a 2D grid of “pixels” (picture elements) \*\***
  - **Each pixel can take on a unique color value**



**\*\* Kayvon will strongly challenge this notion of a pixel “as a little square” next class. But let’s go with it for now. ;-)**



# Flat panel displays



**Low-Res LCD Display**



**High resolution color LCD, OLED, ...**

B.Woods, Android Pit

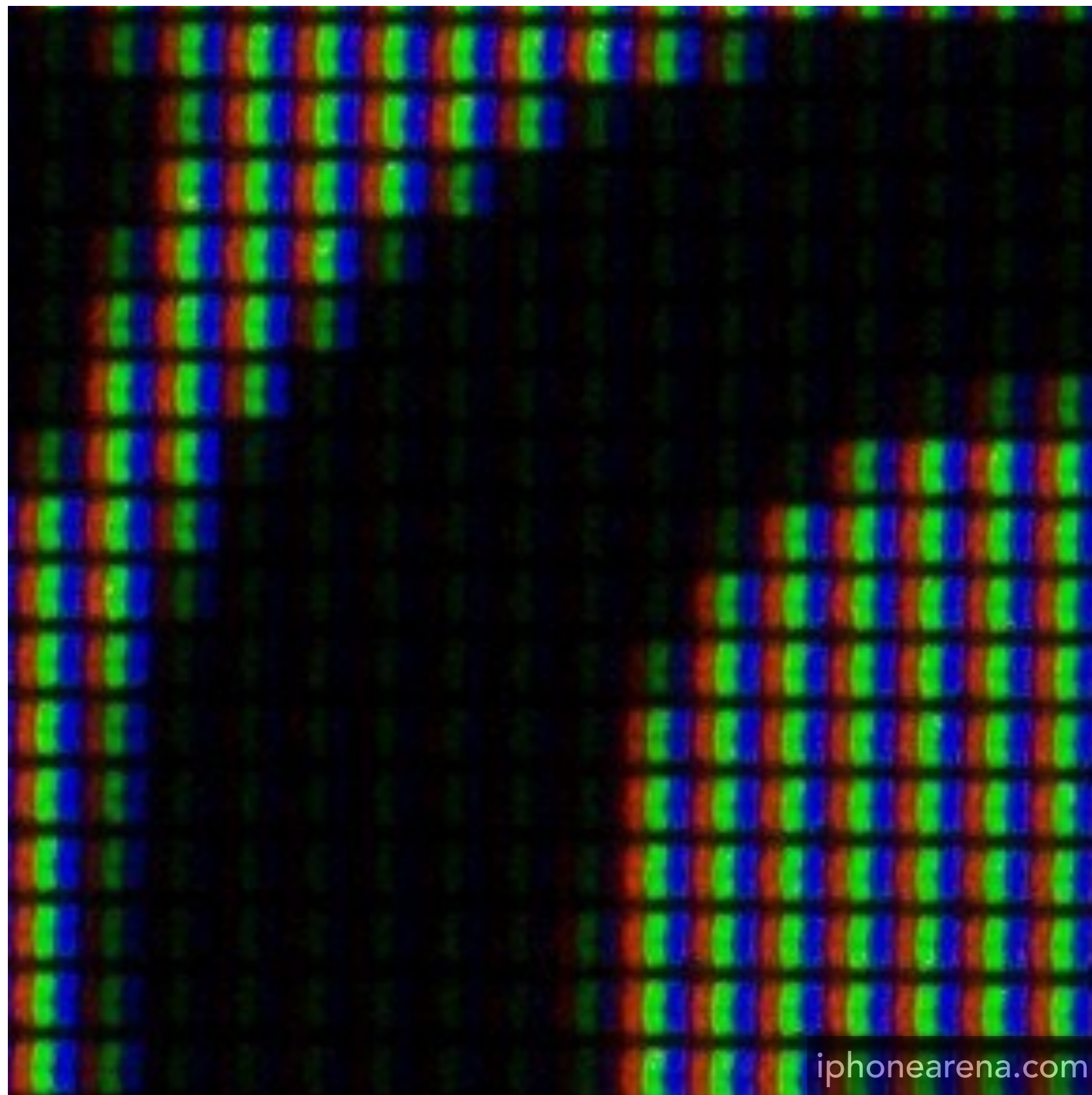


# Close up photo of pixels on a modern display

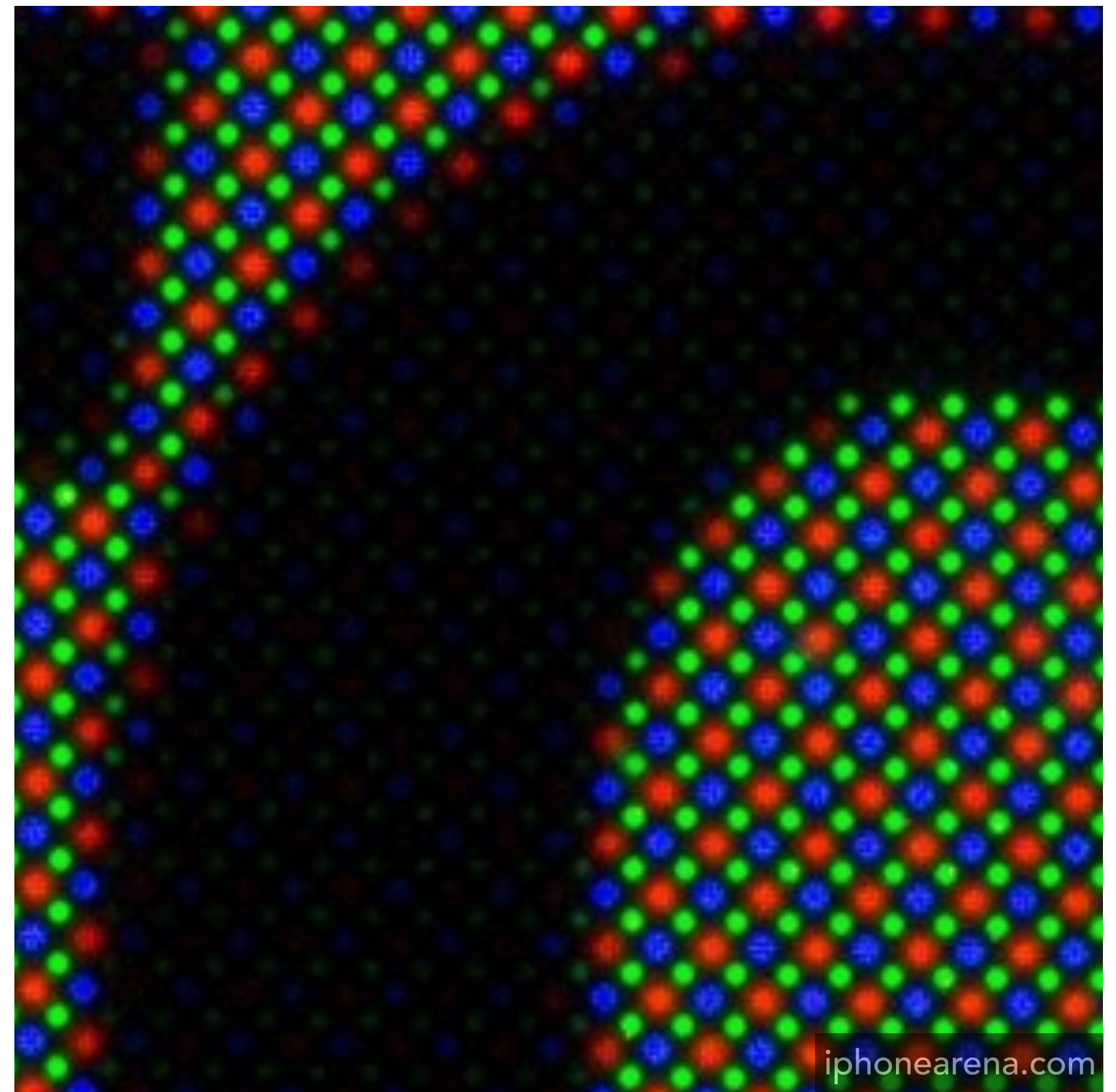




# LCD screen pixels (closeup)



**iPhone 6S**

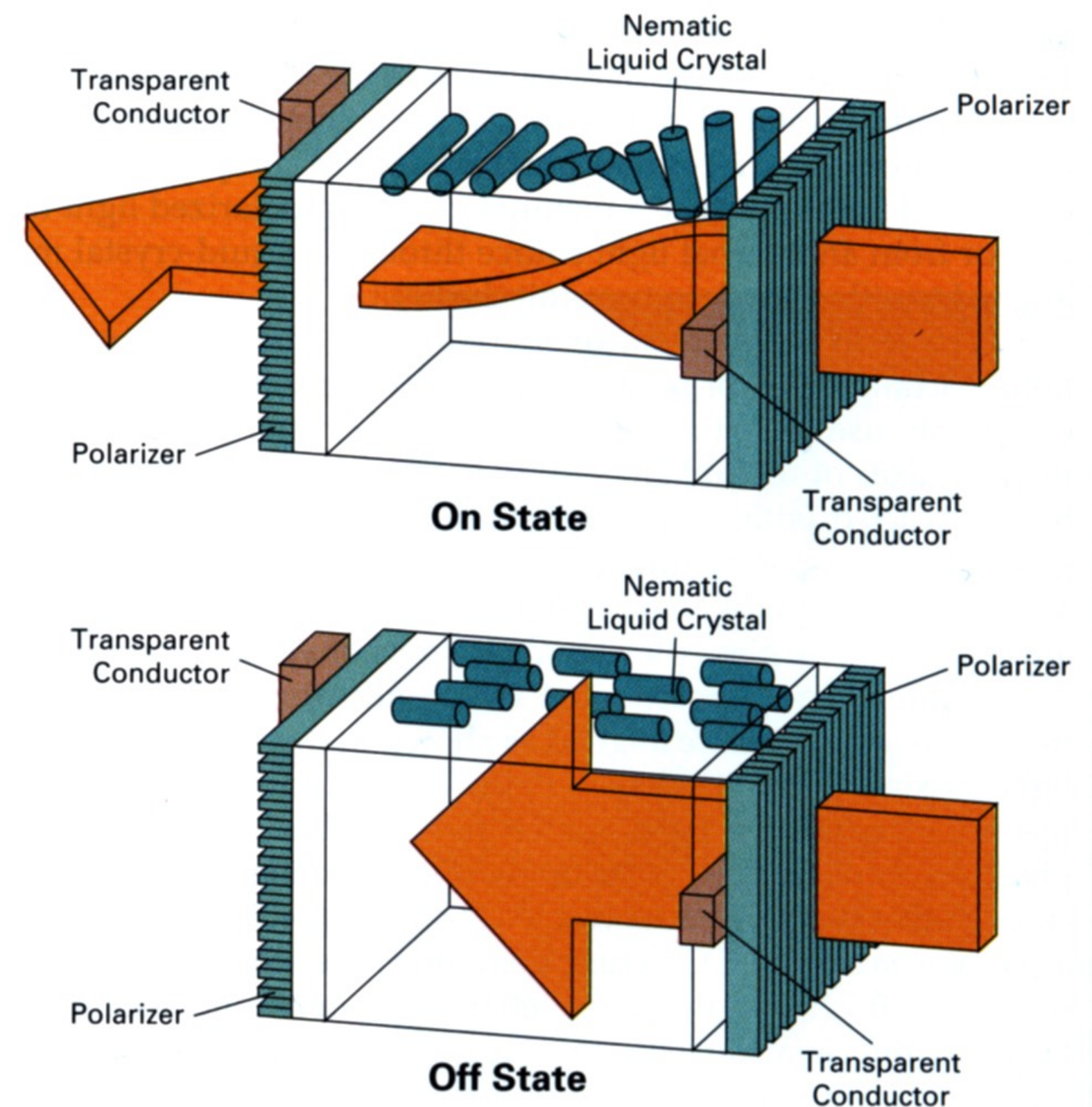


**Galaxy S5**



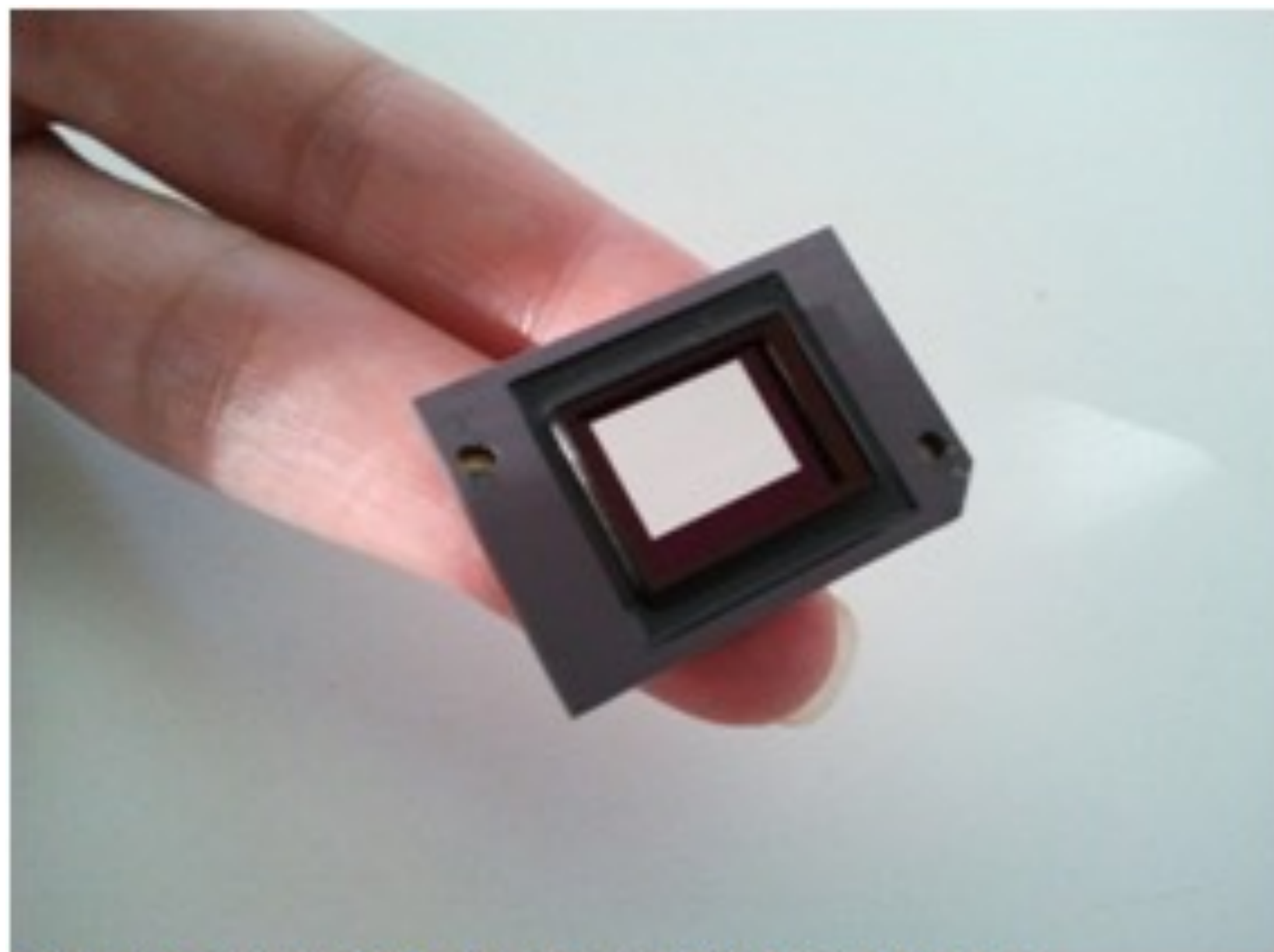
# LCD (liquid crystal display) pixel

- Principle: block or transmit light by twisting polarization
- Illumination from backlight (e.g. fluorescent or LED)
- Intermediate intensity levels by partial twist

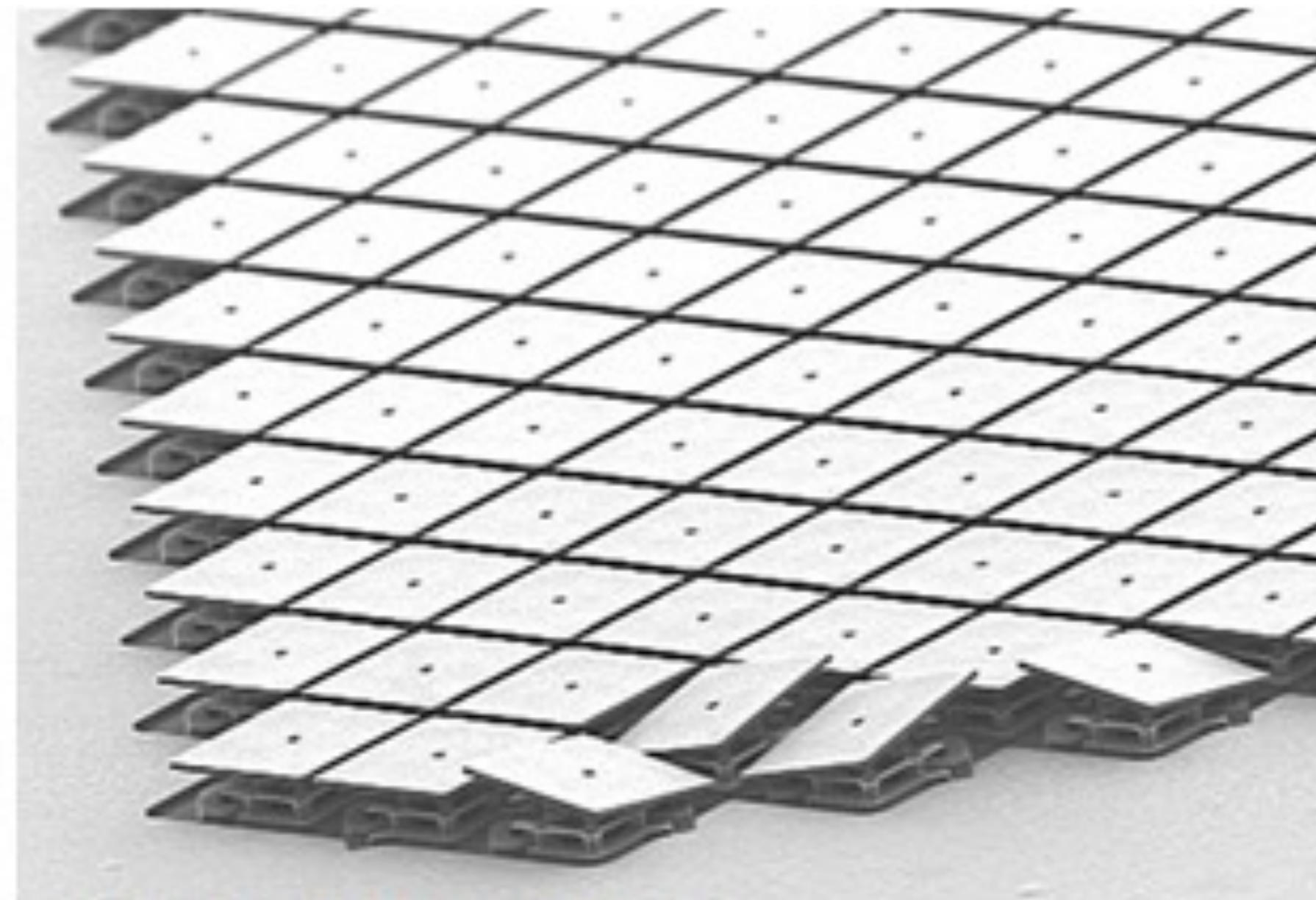




# DMD projection display



DIGITAL MICRO MIRROR DEVICE (**DMD**)  
(**SLM** - Spatial Light Modulator)



MICRO MIRRORS CLOSE UP

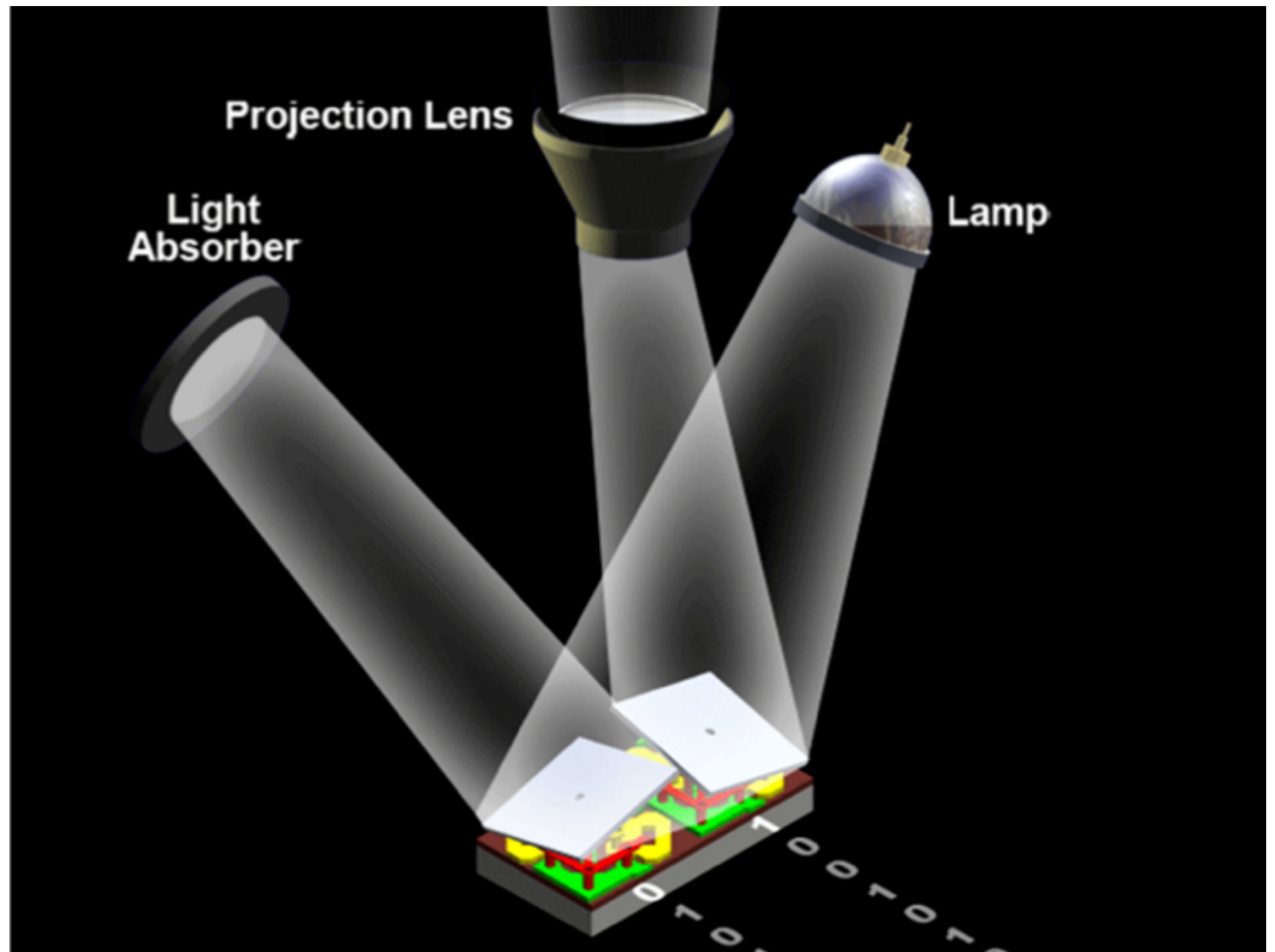
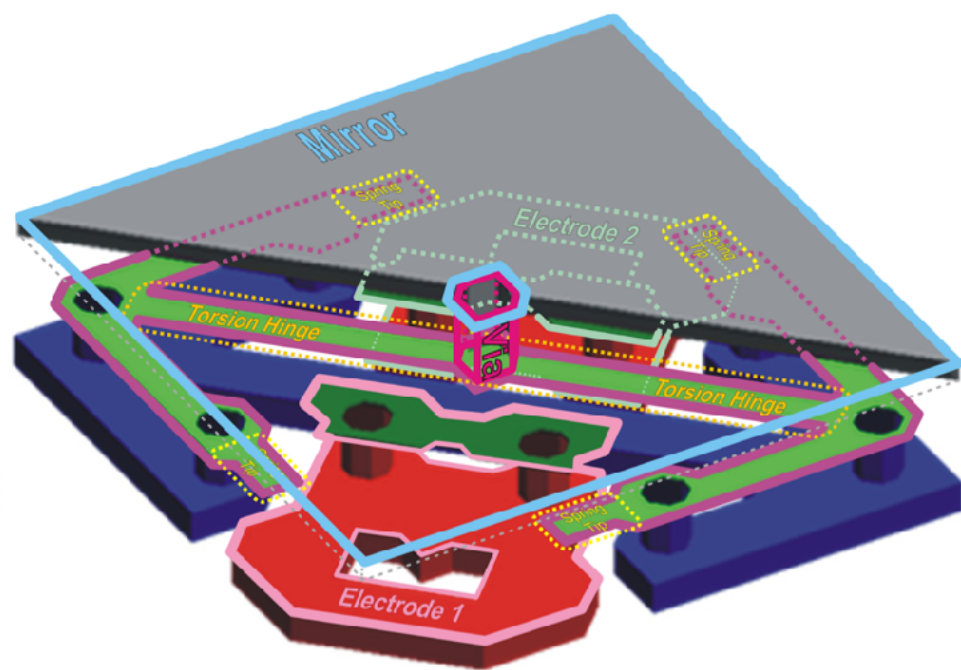
[Y.K. Rabinowitz; EKB Technologies]

**Array of micro-mirror pixels**

**DMD = Digital micro-mirror device**



# DMD projection display



[Texas Instruments]

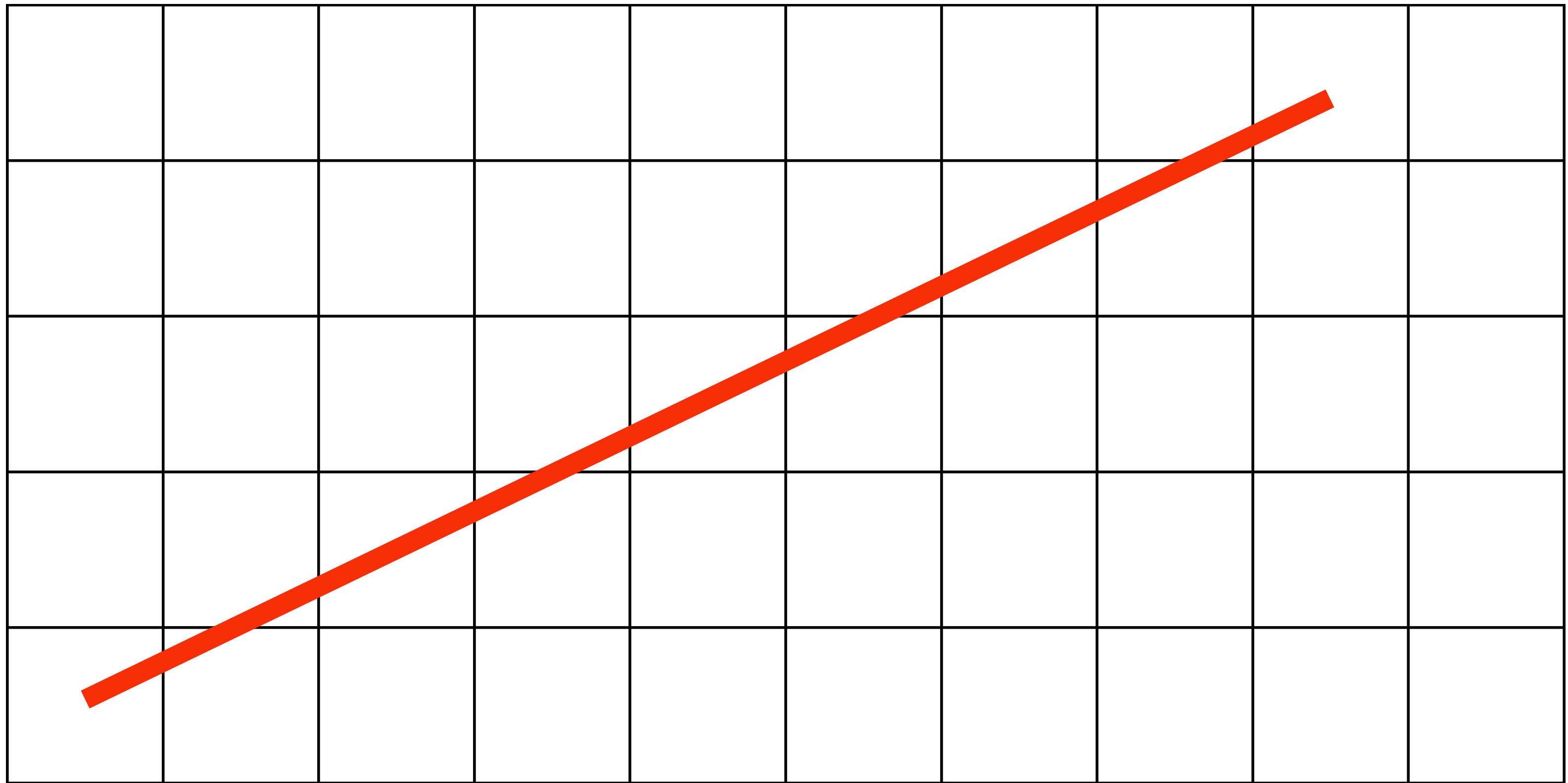
**Array of micro-mirror pixels**

**DMD = Digital micro-mirror device**



# What pixels should we color in to depict a line?

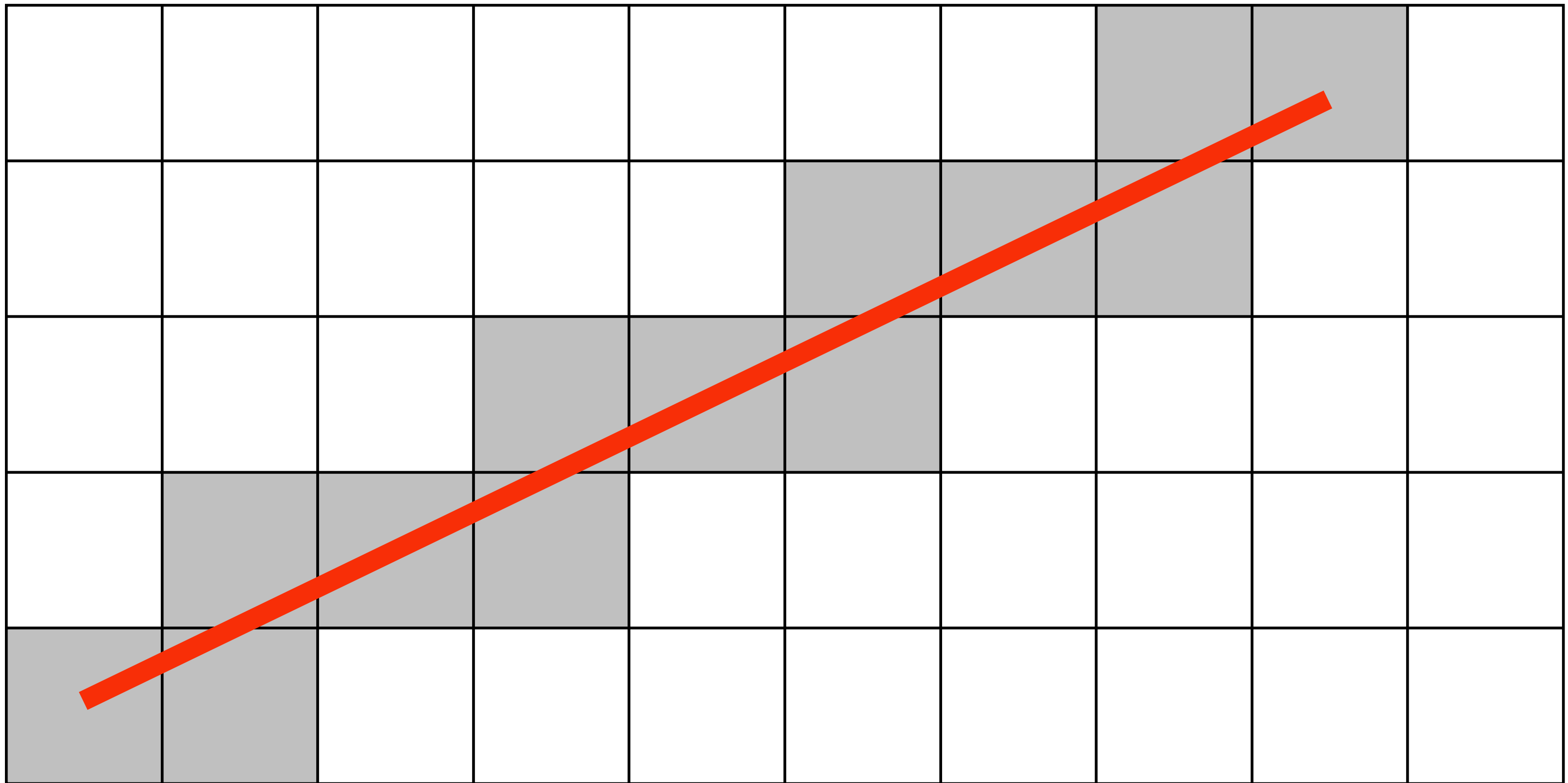
**“Rasterization”**: process of converting a continuous object (a line, a polygon, etc.) to a discrete representation on a “raster” grid (pixel grid)





# What pixels should we color in to depict a line?

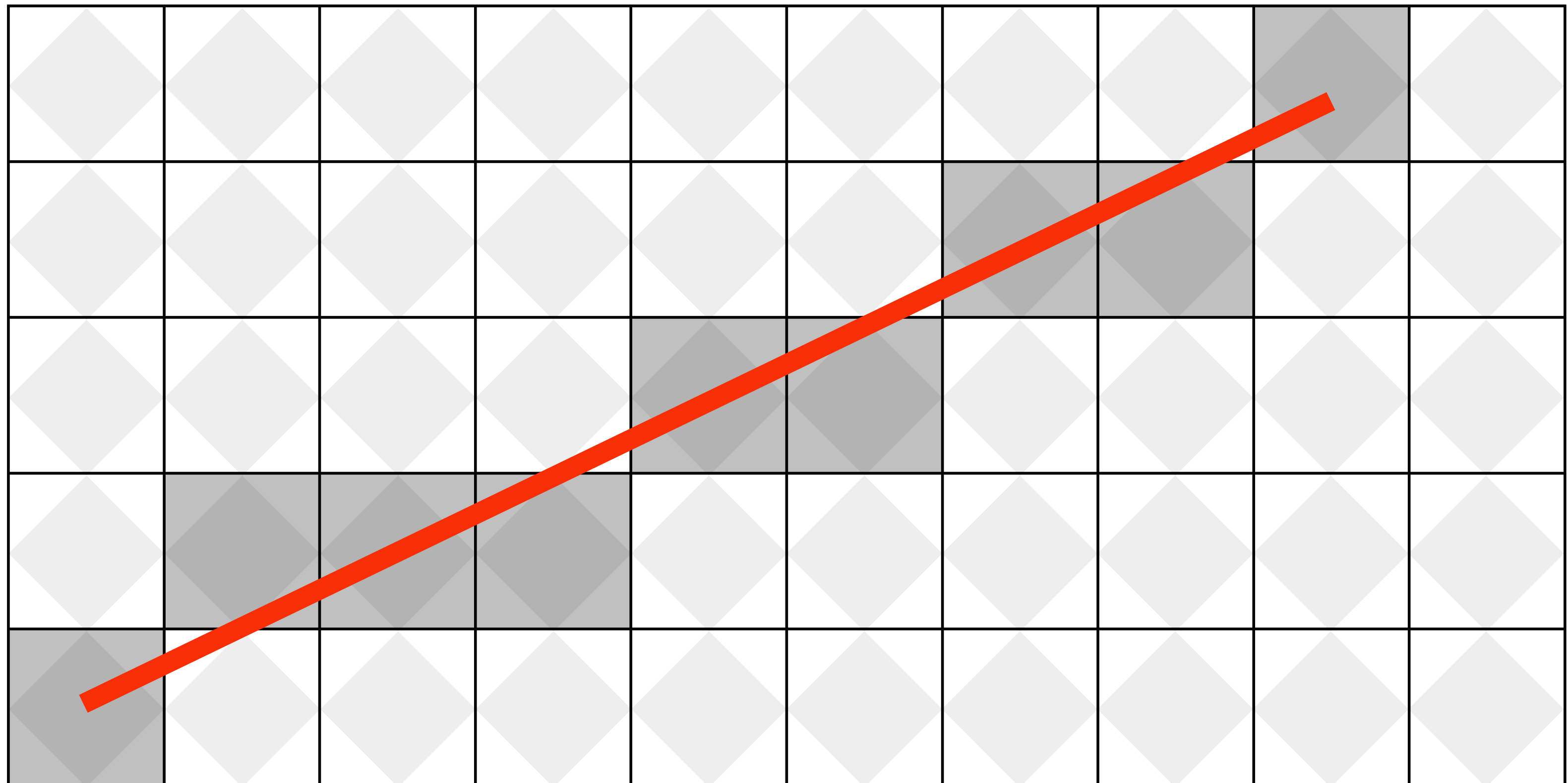
**Light up all pixels intersected by the line?**





# What pixels should we color in to depict a line?

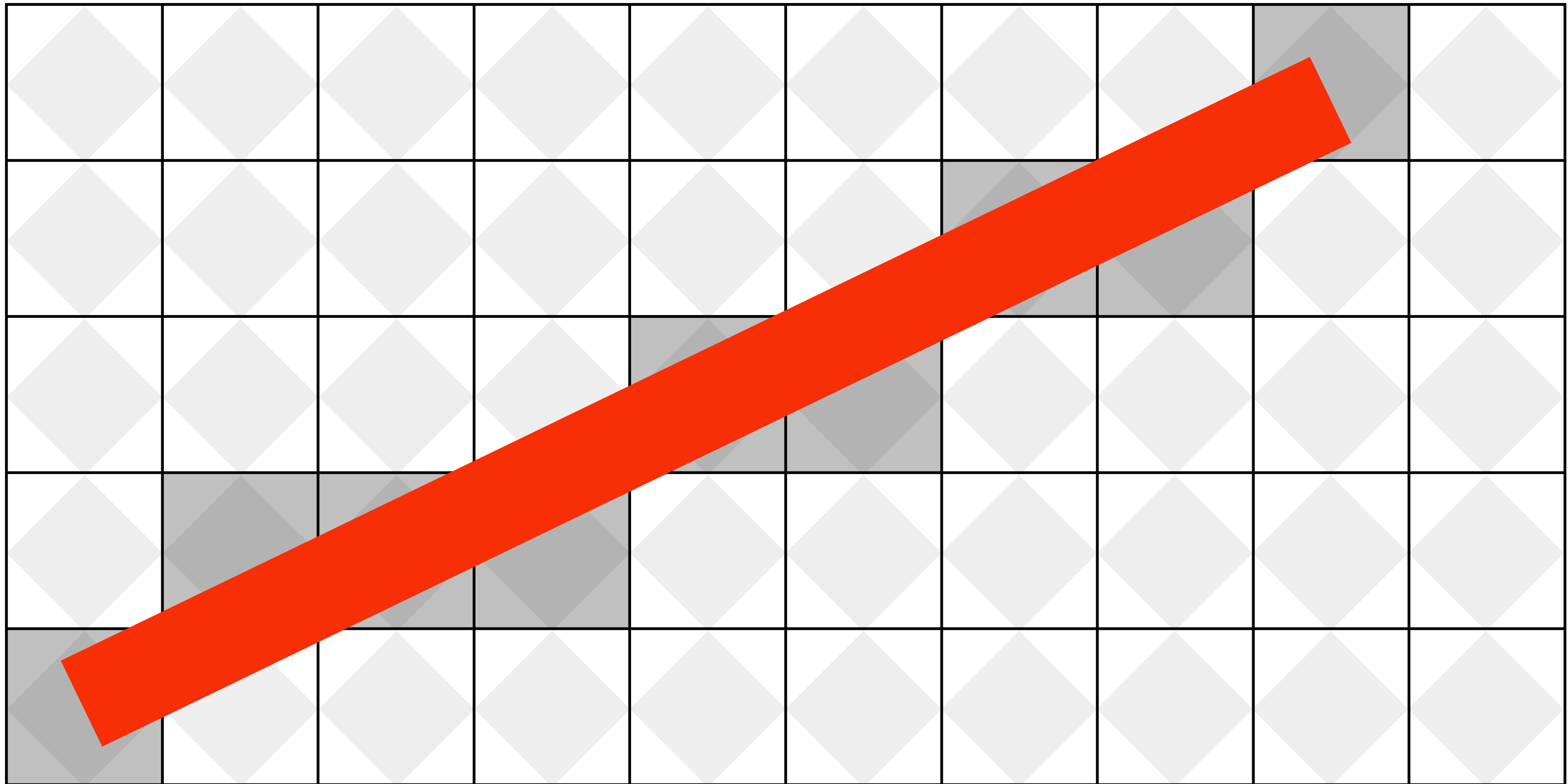
**Diamond rule (used by modern GPUs):  
light up pixel if line passes through associated diamond**





# What pixels should we color in to depict a line?

**Is there a right answer?  
(consider a drawing a “line” with thickness)**





# How do we find the pixels satisfying a chosen rasterization rule?

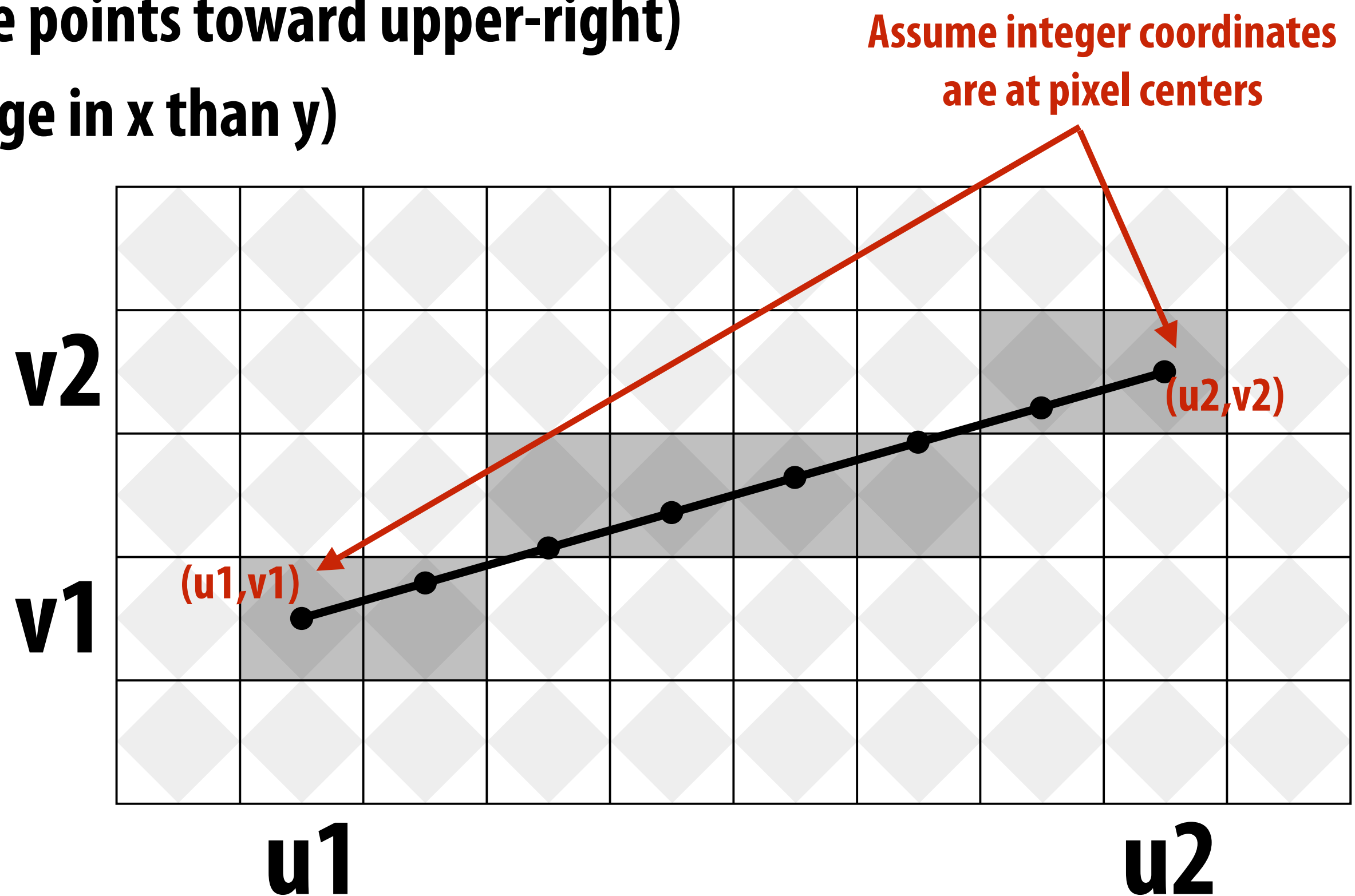
- Could check every single pixel in the image to see if it meets the condition...
  - $O(n^2)$  pixels in image vs. at most  $O(n)$  “lit up” pixels
  - *must* be able to do better! (e.g., seek algorithm that does work proportional to number of pixels in the drawing of the line)



# Incremental line rasterization

- Let's say a line is represented with integer endpoints:  $(u_1, v_1), (u_2, v_2)$
- Slope of line:  $s = (v_2 - v_1) / (u_2 - u_1)$
- Consider an easy special case:
  - $u_1 < u_2, v_1 < v_2$  (line points toward upper-right)
  - $0 < s < 1$  (more change in x than y)

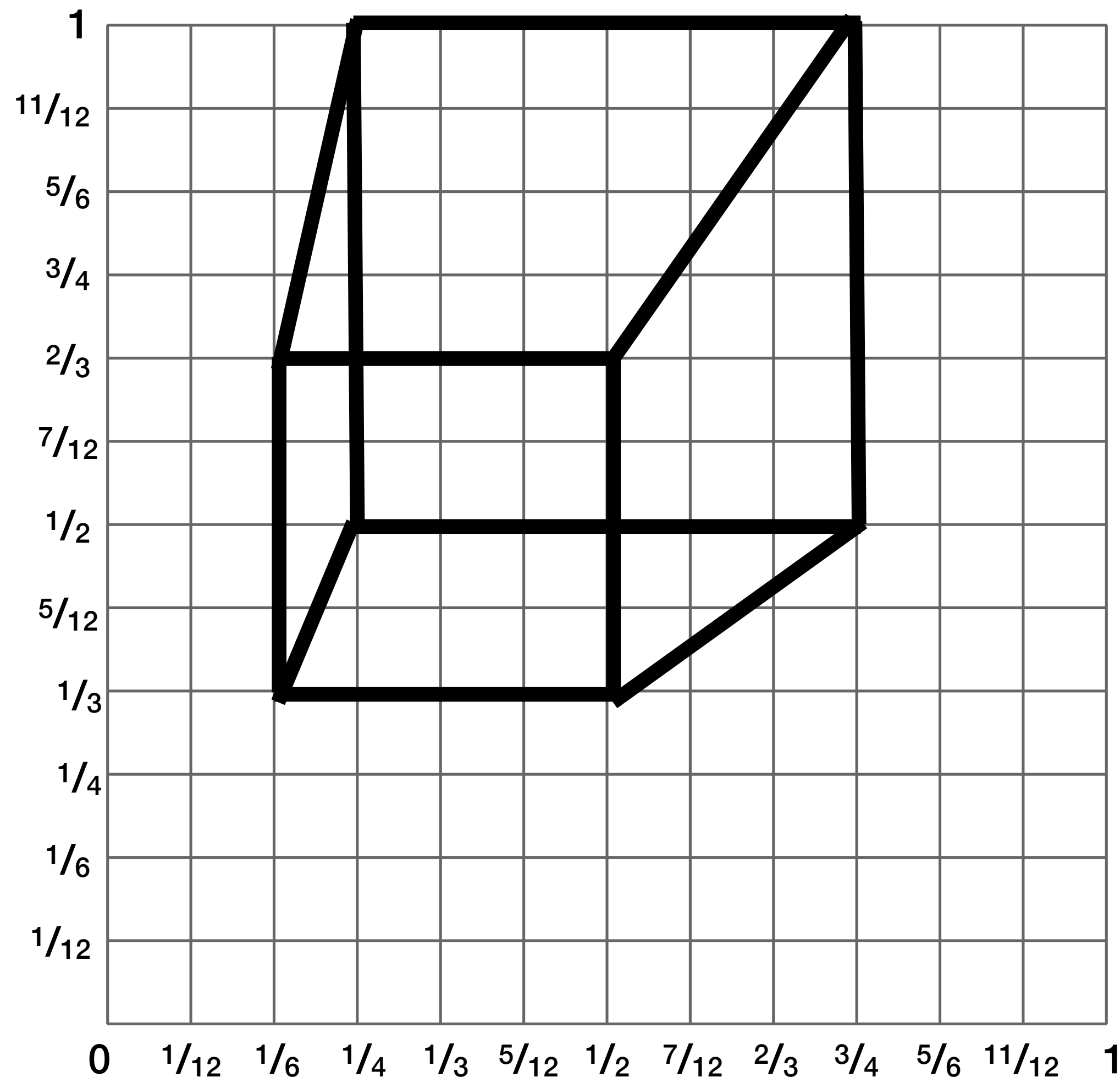
```
v = v1;
for( u=u1; u<=u2; u++ )
{
    v += s;
    draw( u, round(v) )
}
```



**Common optimization: rewrite algorithm to use only integer arithmetic (Bresenham algorithm)**



# Line drawing of cube



## 2D coordinates:

**A:**  $(1/4, 1/2)$

**B:**  $(3/4, 1/2)$

**C:**  $(1/4, 1)$

**D:**  $(3/4, 1)$

**E:**  $(1/6, 1/3)$

**F:**  $(1/2, 1/3)$

**G:**  $(1/6, 2/3)$

**H:**  $(1/2, 2/3)$

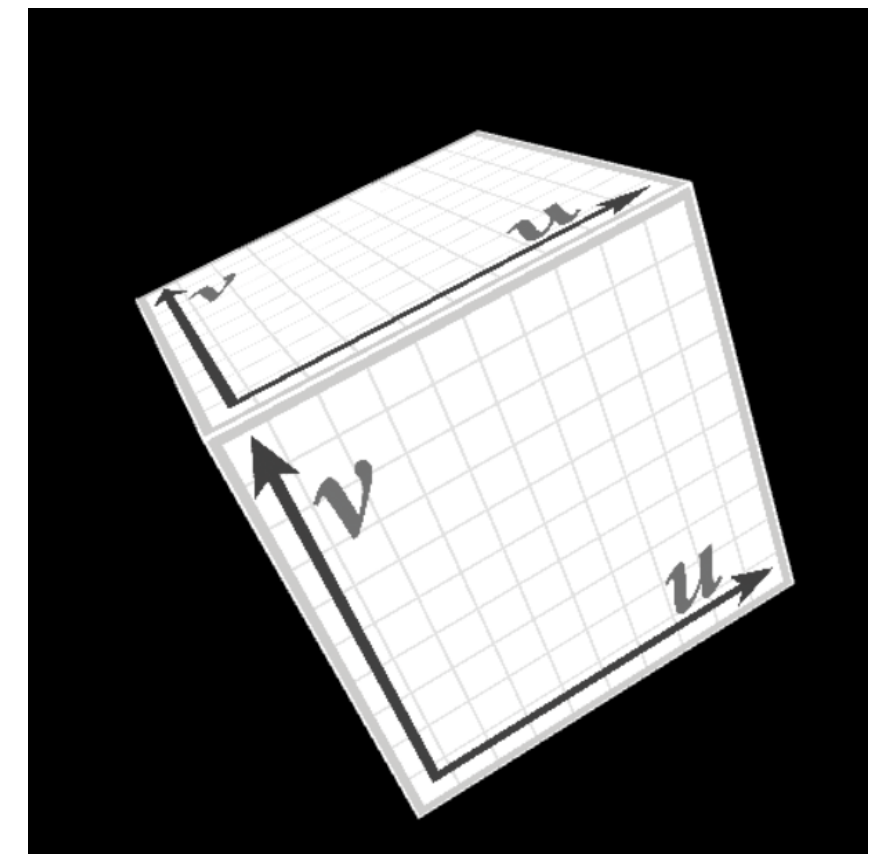
**\* keep in mind, this image is mirrored since we simulated the result of pinhole projection**



**We just rendered a simple line drawing of a cube.**

**But to render more realistic pictures  
(or animations) we need a much richer model  
of the world.**

**surfaces  
motion  
materials  
lights  
cameras**





# 2D shapes



[Source: Batra 2015]



# Complex 3D surfaces



Platonic noid



# Modeling material properties

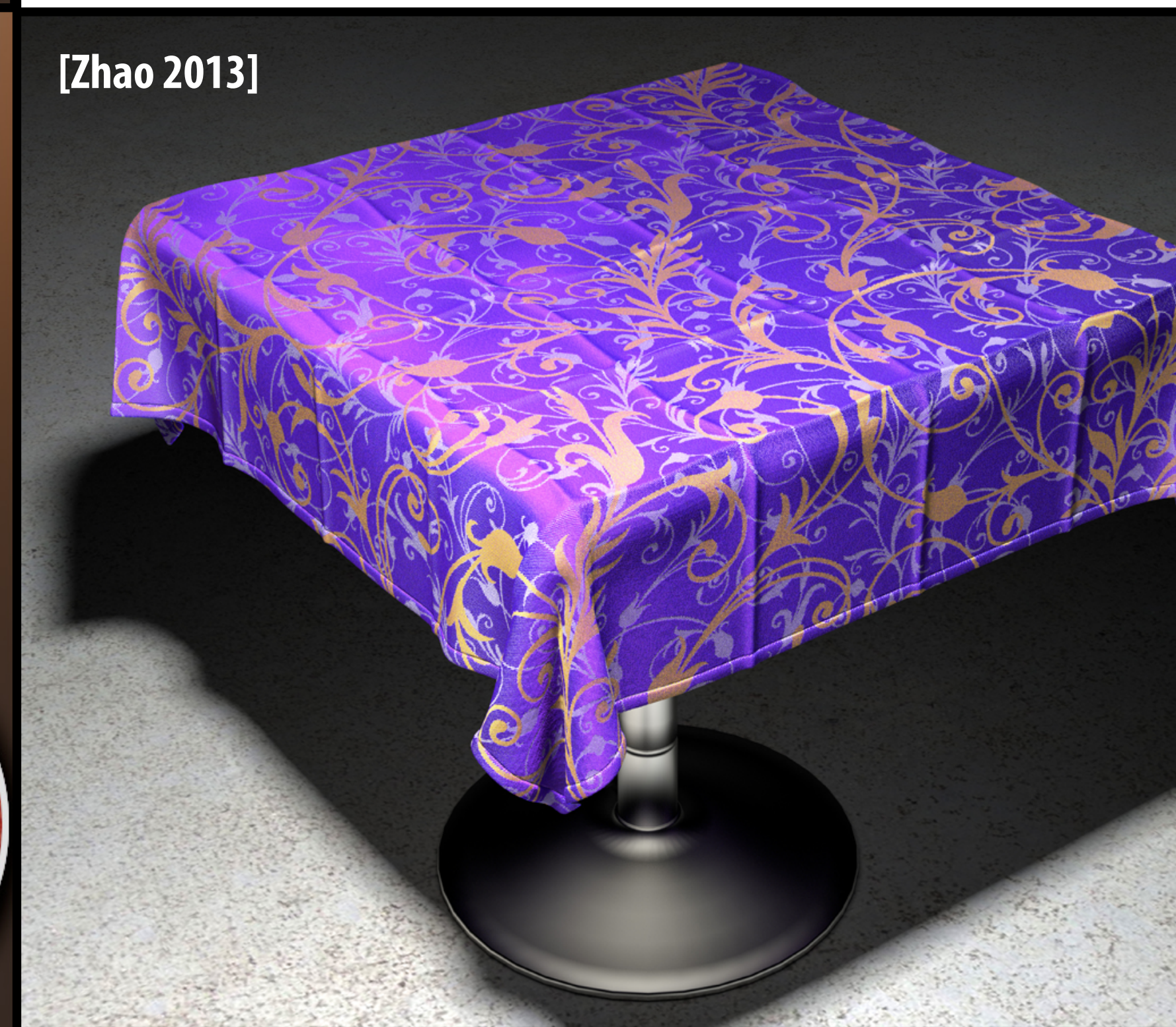


[Wann Jensen 2001]



[Jakob 2014]

[Zhao 2013]





# Realistic lighting environments

Wall-E, (Pixar 2008)





# Animation: modeling motion

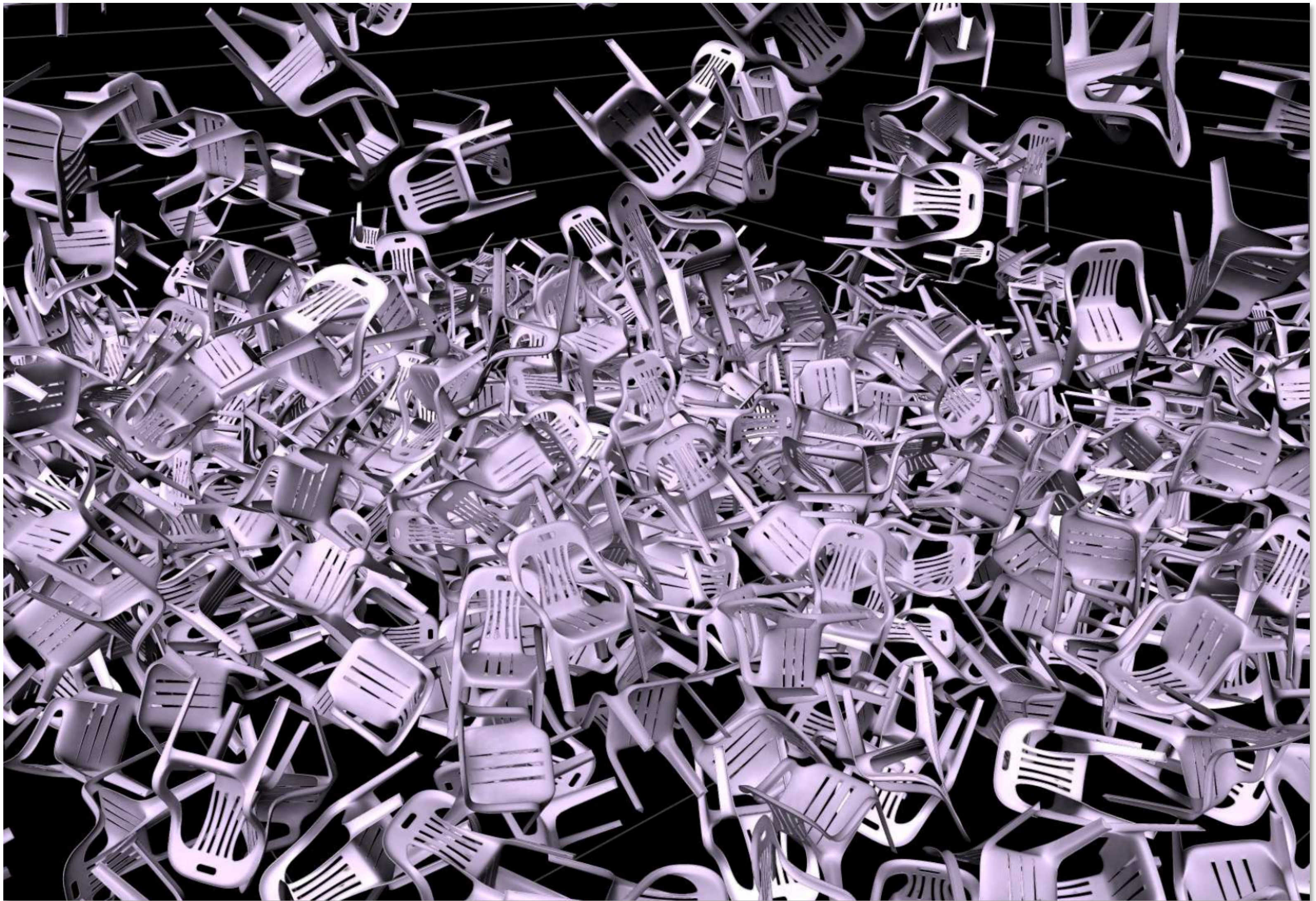
Luxo Jr. (Pixar 1986)



<https://www.youtube.com/watch?v=6G3060o5U7w>



# Physically-based simulation of motion



[https://www.youtube.com/watch?v=tT81VPk\\_ukU](https://www.youtube.com/watch?v=tT81VPk_ukU)

[James 2004]



# Course Logistics



# About this course

- **A broad overview of major topics and techniques in interactive computer graphics: geometry, rendering, animation, imaging**
- **Learn by implementing:**
  - **Focus on implementing fundamental data structures and algorithms that are reused across all areas of graphics**

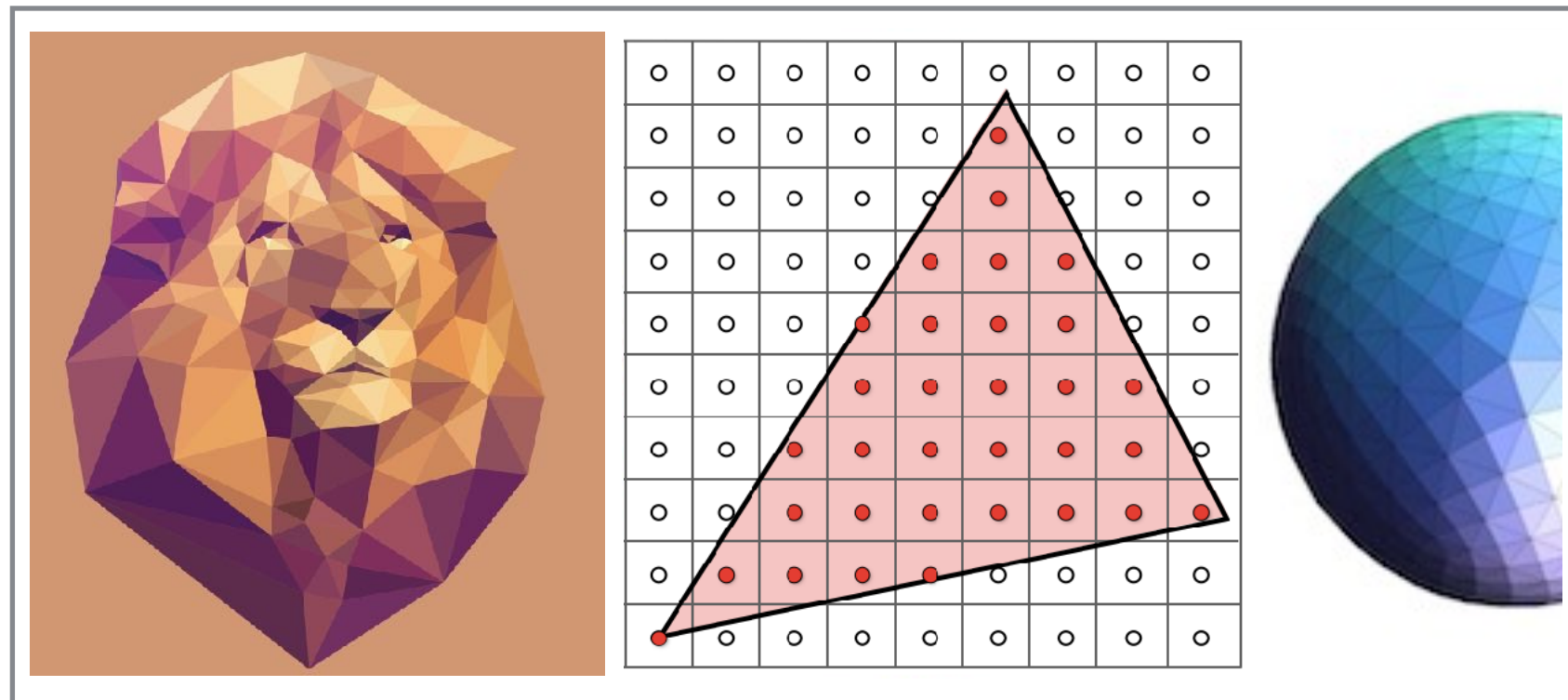


# Getting started

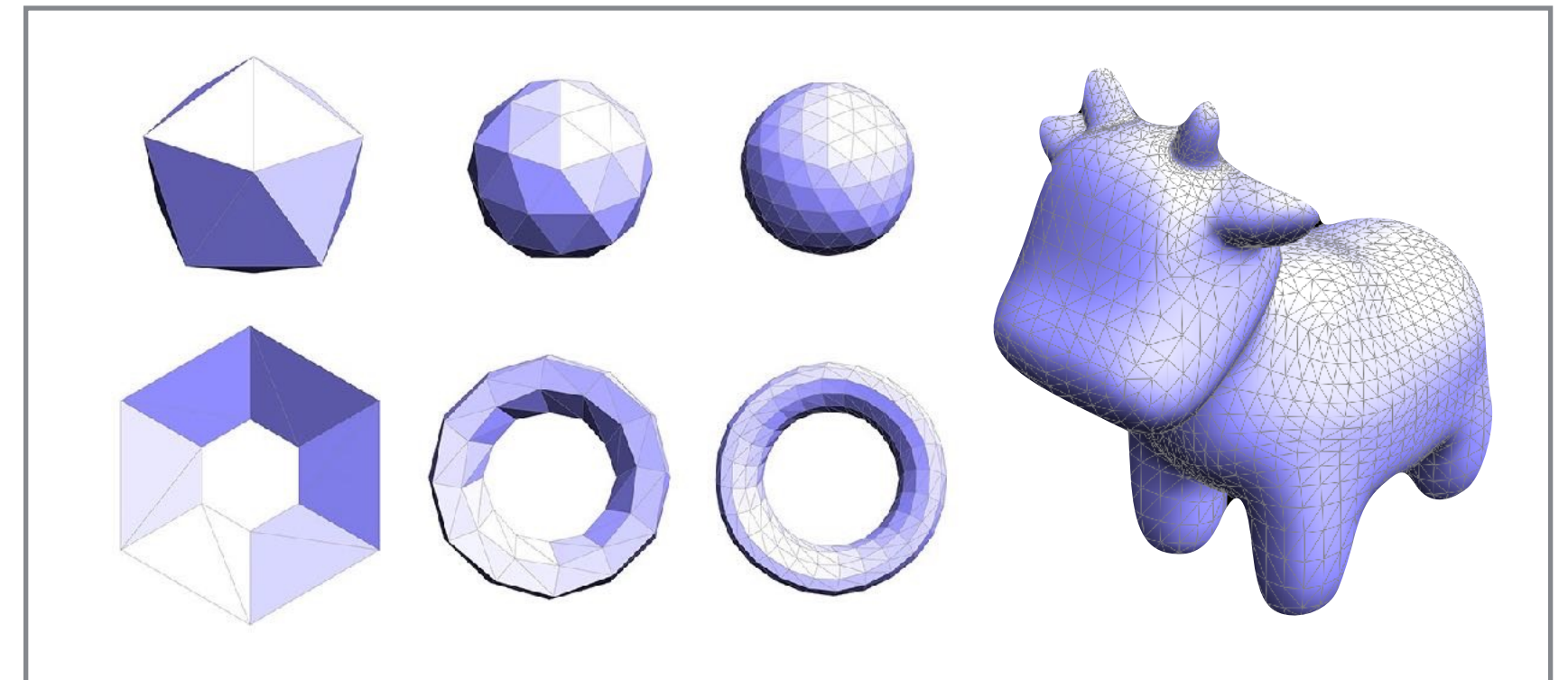
- **Sign up for an account on the course web site**
  - **<http://cs248.stanford.edu>**
- **Sign up for the course on Piazza**
  - **<http://piazza.com/stanford/winter2020/cs248>**
- **There is no textbook for this course, but please see the course website for references (there are some excellent graphics textbooks)**



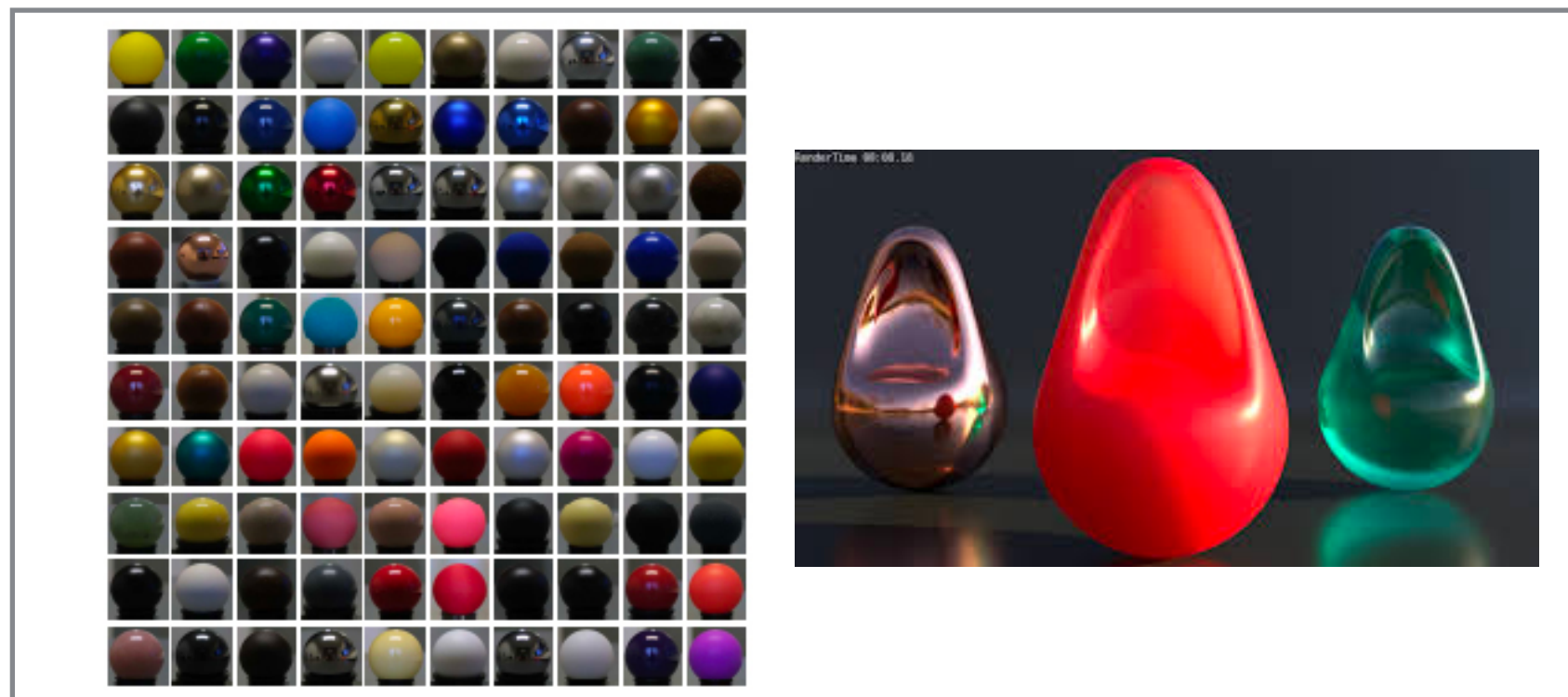
# Course programming assignments



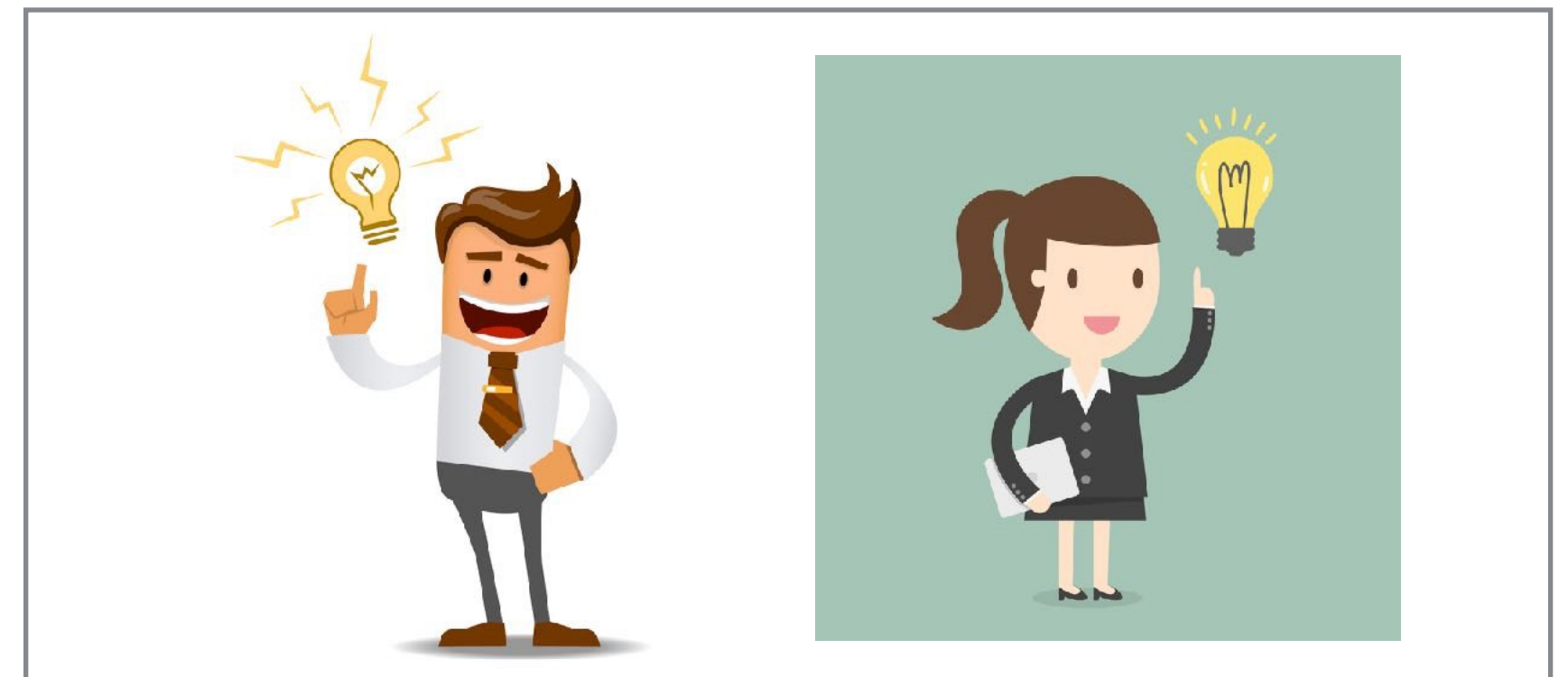
**1. 2D drawing (2 weeks)**



**2. Geometry editing (2 weeks)**



**3. Materials and lighting in a 3D renderer (2 weeks)**



**4. Self-selected project**  
**extend existing project, take on optional**  
**animation project, choose your own**  
**(~3 weeks)**



# Assignments / Grading

- **(40%) Three programming assignments**
  - In teams of up to two students (yes, you can work alone if you wish)
- **(10%) Written exercises (weekly)**
  - Released on Tues night, due Friday 10am (starting next week)
  - Graded on participation only
- **(25%) Final exam**
  - Given in week 9 of the course
- **(25%) Self-selected final project**
  - Extend an earlier assignment, or do your own thing!

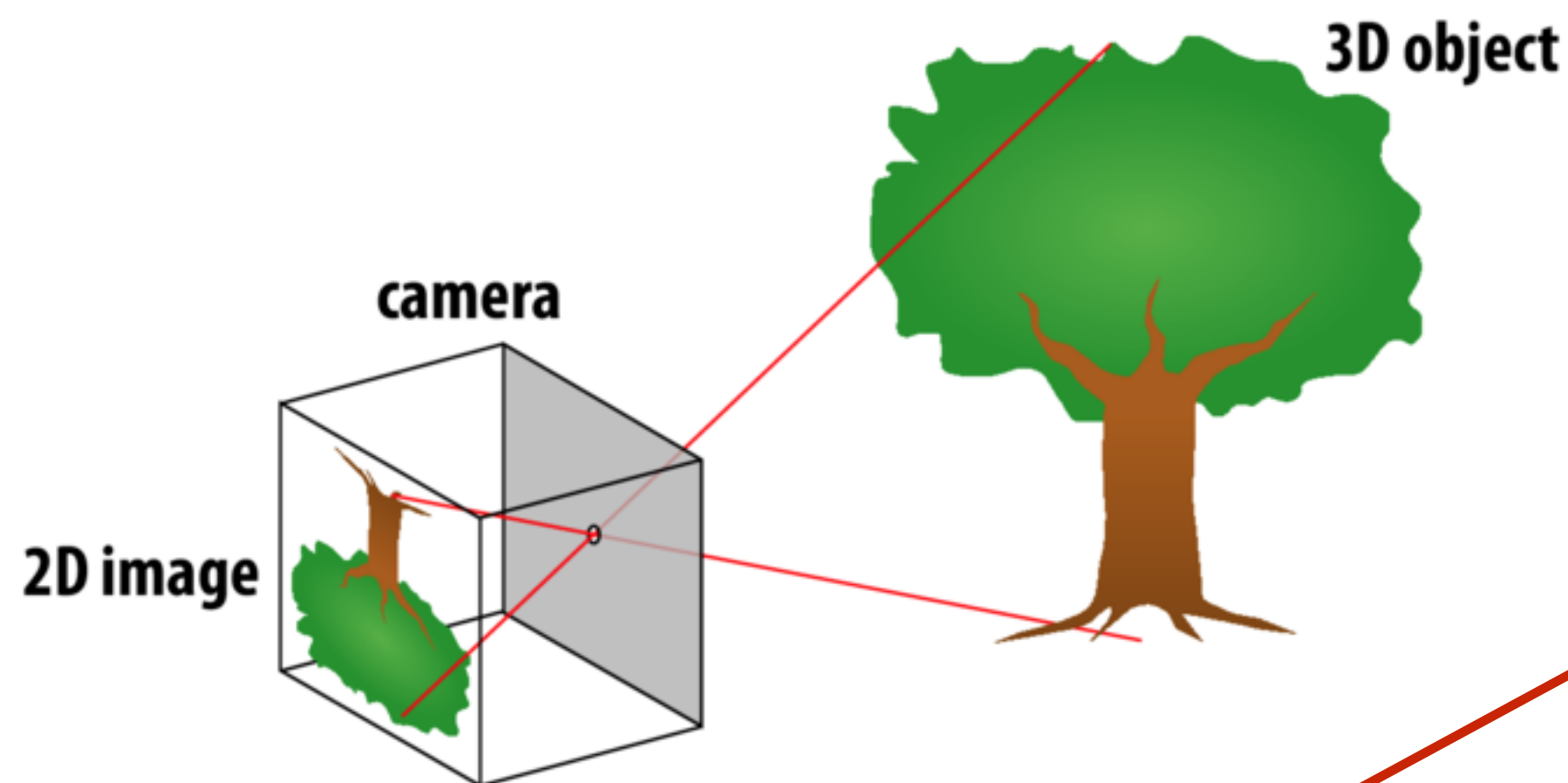


# The course web site

We have no textbook for this class and so the lecture slides and instructor/TA/student discussions on the web are the primary course reference

## Perspective projection

- Objects look smaller as they get further away (“perspective”)
- Why does this happen?
- Consider simple (“pinhole”) model of a camera:



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**kayvonf** about an hour ago

**Question:** During class Keenan asked a question about why do objects look smaller when they are viewed at a distance. I liked one of the arguments made because it appealed to the angle subtended by an object. Could someone elaborate on that here?

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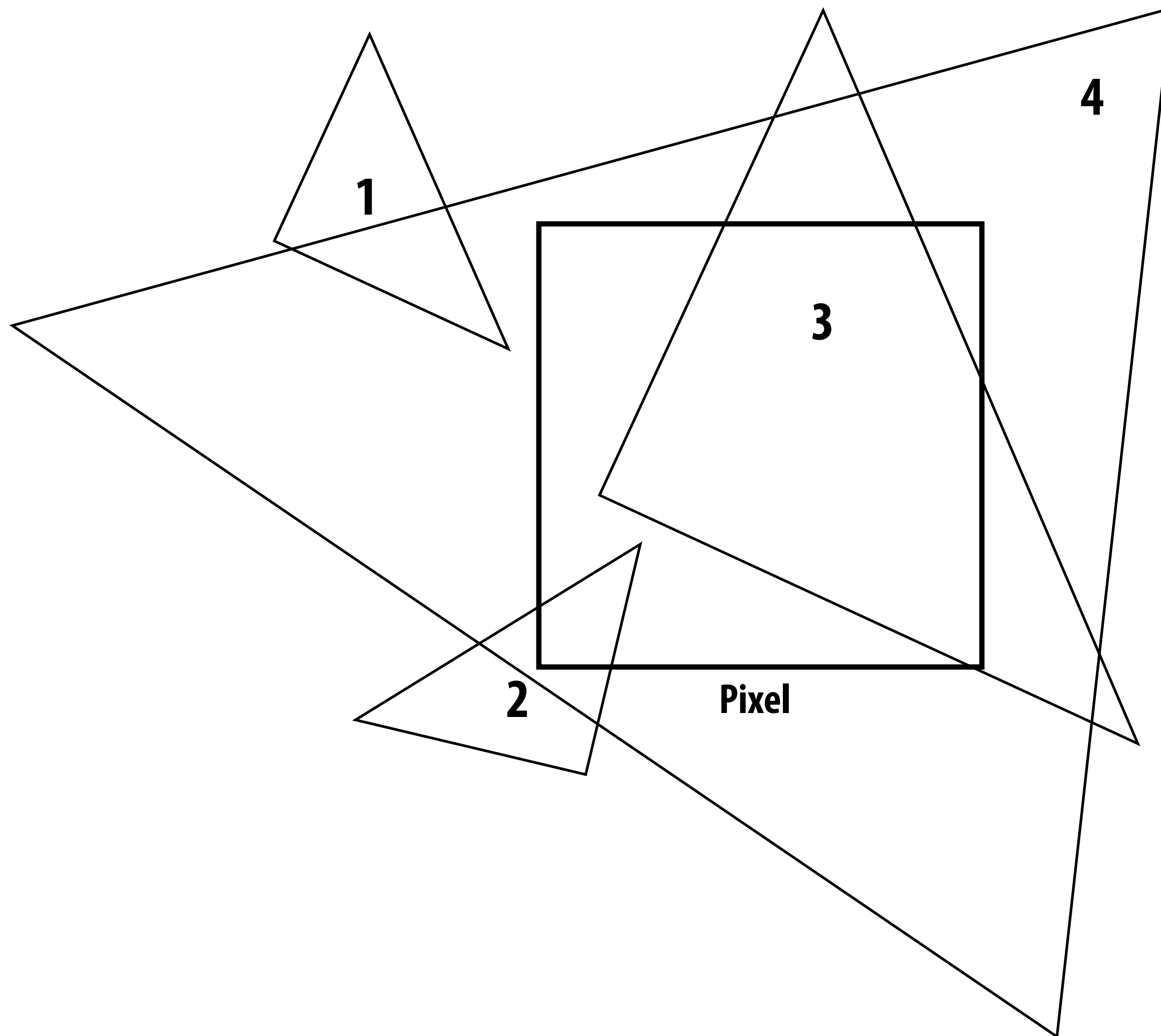
**Slide comments and discussion**



# Thought question for next time:

## What does it mean for a pixel to be covered by a triangle?

Question: which of these four triangles “cover” this pixel?





# See you next time!

**Next time, we'll talk about drawing a triangle**

- And it's a lot more interesting than it might seem...**
- Also, what's up with these "jagged" lines?**

